

Demonstration of a Reflectarray with Near-field Amplitude and Phase Constraints as Compact Antenna Test Range Probe for 5G New Radio Devices

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Abstract—In this work a reflectarray is proposed to be used as a probe of a reduce and portable Compact-Antenna-Test-Range for 5G new radio devices. The reflectarray works at 28 GHz and produces a quiet zone in the near-field region of the antenna. Considering that the quiet zone specifications are established in terms of the amplitude and phase ripple, a synthesis technique is presented to optimize the near-field in the Fresnel region of a reflectarray with amplitude and phase constraints. The proposed technique is based on the generalized Intersection Approach, using the Levenberg-Marquardt algorithm as its backward projector obtaining a novel technique in near-field synthesis. This technique is applied to improve the quiet zone radiated by the proposed reflectarray, overcoming the amplitude and phase limitations of the initial configuration. The solution provided by this process is used to design and manufacture a reflectarray based on a three-parallel-dipole cell. Finally, the prototype is measured in a near-field planar range facility in order to evaluate the radiated quiet zone and demonstrate the methodology. The prototype satisfies the tight requirements in amplitude and phase, obtaining promising results.

Index Terms—Near-field synthesis, compact antenna test range, CATR, reflectarray, measurement system.

I. INTRODUCTION

THROUGHOUT the last decades antenna measurement systems have been constantly developed in order to adapt them to the new technological requirements. In a first approach, far-field ranges were used to directly measure the radiation pattern of the Antenna Under Test (AUT). Since the AUT should be placed in the far-field of the probe, these

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ranges usually require large dimensions, which leads to really bulky systems. Conversely, the near-field scanning ranges only measure the near-field of the AUT [1], therefore the system dimensions are notably reduced. However, a large amount of near-field data has to be acquired in order to perform a Near-Field to Far-Field (NF-FF) transformation to get the field value, demanding long time measurements and a high stable measurement system.

Compact Antenna Test Ranges (CATR) [2] are an attractive alternative to replace far- and near-field scanning ranges. This solution provides a system with the ability of measuring the radiation pattern directly, even though the AUT is within the near-field region of the probe. These systems are based on the existence of an area within the Fresnel region of the probe known as quiet zone. Such area virtually behaves as an uniform plane wave, and is suitable for antenna measurements in a relatively compact space.

On the other hand, new technological needs have appeared together with the popularity of the (sub)millimeter band applications. Particularly, the deployment of 5G communications in the three bands of 28, 39 and 60 GHz [3], [4], [5], automotive radars at 77 GHz [6], [7] or space communications [8], [9] among others. Hence, antenna measurement systems need to evolve and fulfill these new requirements, where CATRs are a suitable candidate to test these new devices. These systems are traditionally based on a parabolic reflector configuration, which provides a solution that collimates the incoming field radiated by its feed, that typically is a horn, in a certain direction where the quiet zone can be found. The geometrical properties of the parabolic reflector allows to directly obtain a plane wave, whilst the amplitude is conditioned by the amplitude taper of the incident field. However, additional drawbacks appears at those frequencies. Mainly, parabolic reflectors present particular issues in terms of their size or manufacturing process, which needs low surface errors and therefore increase the expenses.

In [10] and [11] the use of dielectric lenses was studied as an alternative to overcome the reflector drawbacks, though they do not obtain a sufficient surface accuracy. Hereinafter, it was introduced the concept of a hologram-based CATR [12]. Mainly, a planar hologram is used to provide a solution similar

to parabolic reflectors, where this planar structure behaves as the collimating element of an incoming field provided by a feed. Then, the quiet zone may be found in the radiated plane wave. The advantage of using holograms regards on their low-cost and easy manufacturing process, reducing the surface accuracy requirements. This proposal has clearly demonstrated good performances in (sub)millimeter bands, even when it is compared with a planar near-field scanning [13].

Regarding the quiet zone performances, it should be highlighted that its size directly depends on the equivalent aperture (D) of the probe, leading to use large electrical antennas and, thus bulky probes. i.e. in [13] a hologram of more than one meter in each direction is used to get a quiet zone of $70\text{ cm} \times 45\text{ cm}$ equivalent to a $46\% \times 32\%$ of the hologram aperture. Beside that, a near-field volume is theoretically considered quiet zone whenever its maximum ripple in amplitude and phase is lower than 1 dB and 10° respectively. However, it can be found implemented systems in that are operative with higher peak-to-peak ripples [13]. Slight increments on the amplitude ripple have small effects on the radiation pattern measurement, while errors in the phase distort the gain and sidelobe levels or fill the nulls [14].

Another potential alternative to reflectors and holograms is the reflectarray antenna, which also has the capacity to transform a spherical wave into a plane wave, wherein the quiet zone may be located. Reflectarray antennas are planar structures based on printed technology, which reduces the surfaces error requirements and the manufacturing costs. These antennas have widely demonstrated good performances in multiple applications with tight specifications, such as satellite communications, specially Direct Broadband Satellite (DBS) missions [15], innovative wireless communications [16] or femtocells for 5G indoor communications [17]. In [18] the quiet zone radiated by a reflectarray is evaluated and improved using a near-field synthesis in order to reduce both amplitude and phase ripples. This synthesis is based on a direct optimization technique that, despite reaching acceptable performance on the quiet zone, the obtained phase variation along the reflectarray surface is too high for a potential implementation. This leads to a main drawback of these techniques, the degree of freedom of their solutions and their hardly implementation into a design. In addition, there is a strong limitation in the number of optimization variables that can be managed. One approach to overcome these issues is the generalized Intersection Approach for far-field synthesis, which can efficiently deal with a large amount of optimization variables [19], [20], which also can be related with the antenna geometry. Thus, the layout of the antenna can be considered into the optimization process based on Intersection Approach, leading to more feasible solutions than the reached in classic direct optimization techniques. In [21] the Intersection Approach is introduced to synthesize the near-field radiated by a reflectarray but just with amplitude constraints, resulting in a degradation of the phase front.

In this work, the generalized Intersection Approach is extended to synthesised the near-field with both amplitude and phase constraints, by only optimizing the phase distribution of the reflection coefficients of the reflectarray elements.

Then, a squared reflectarray comprises by 44×44 elements ($188.76 \times 188.76\text{ mm}^2$) is proposed to generate a quiet zone at 500 mm (46.6λ) with a working frequency of 28 GHz . The width of the quiet zone is 100 mm , the height is 100 mm , equivalent to more than a 53% of the antenna aperture width in the x and y axes, which is obtained through a phase-only synthesis including near-field amplitude and phase constraints, using the generalized Intersection Approach. The obtained phase distribution reaches to satisfy the quiet zone requirements and it is suitable to perform a design. The elementary reflectarray element is based on three parallel dipoles, which obtain an enough phase-shift to cover a 360° range [22]. The design is performed and measured in a planar range facility to evaluate the generated quiet zone. Finally, measurements are analysed to validate the proposed technique and the utility of reflectarrays as a probe in a small and portable CATR systems for 5G new radio devices measurements.

II. INTERSECTION APPROACH FOR NEAR-FIELD SHAPING

A. Classical Interseccion Approach

Unlike the classical optimization algorithms, where the algorithm looks for the minimization of a cost function, the Intersection Approach (IA) searches the intersection between two sets. Those sets are defined as: 1) the set of the fields that complies the desired specifications (\mathcal{M}), and 2) the set within all the field that can be generated by the antenna (\mathcal{R}). This intersection search is based on an iterative process of alternative projections, which are performed by two operations in each iteration:

$$\vec{E}_{NF}^{i+1} = \mathcal{B} \left[\mathcal{F} \left(\vec{E}_{NF}^i \right) \right] \quad (1)$$

where \mathcal{F} is the forward projector, which is used to project a point of \mathcal{R} onto \mathcal{M} ; \mathcal{B} is the backward projector that allows to retrieve from one point of \mathcal{M} onto \mathcal{R} ; and \vec{E}_{NF}^i is the field radiated by the antenna at the i -iteration. The ideal results of this iterative process are a field that belongs concurrently to both sets, therefore obtaining a field within the specifications but also feasible to be radiated by the antenna geometry.

The Intersection Approach concept can be also explained in terms of the tangential field at the aperture (\vec{E}_{AP}) and its radiated fields (\vec{E}_{NF}). If a single-offset reflectarray configuration is taken as reference (see Fig. 1), and the flowchart shown in Fig. 2 is followed, the electric tangential field at the reflectarray aperture is computed as:

$$\vec{E}_{AP}(\vec{r}_m) = \mathbf{R}^m \cdot \vec{E}_{inc}(\vec{r}_m) = \begin{pmatrix} \rho_{xx}^m & \rho_{xy}^m \\ \rho_{yx}^m & \rho_{yy}^m \end{pmatrix} \cdot \begin{pmatrix} E_{x,inc} \\ E_{y,inc} \end{pmatrix} \quad (2)$$

where \mathbf{R} is the reflection coefficient matrix that relates the complex amplitude of the tangential components of the incident field, $E_{x,inc}$ and $E_{y,inc}$, and the reflected electric field by the m th-element of the reflectarray located at the point \vec{r}_m . This reflection matrix is obtained in each reflectarray cell under local periodicity assumption [23], and its elements are the direct reflection coefficients (ρ_{xx}^m and ρ_{yy}^m) and the cross reflection coefficients (ρ_{xy}^m and ρ_{yx}^m).

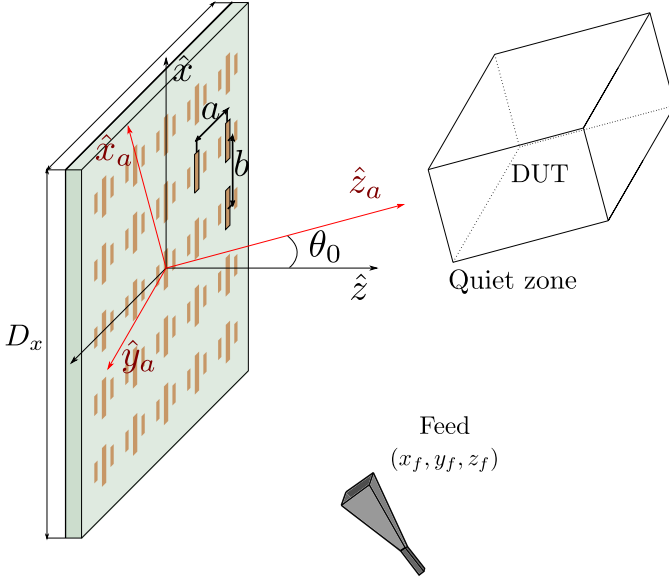


Fig. 1: Scheme of a CATR system based on an offset configuration reflectarray antenna.

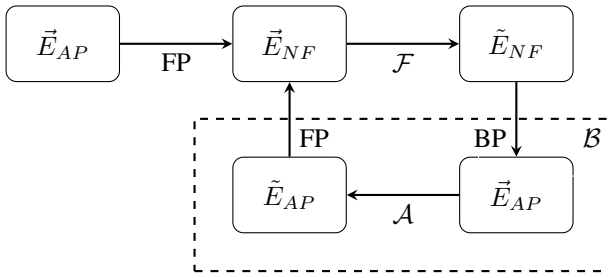


Fig. 2: Flowchart of the classical Intersection Approach.

However, in (2) when dealing with a Phase-Only Synthesis (POS) of the reflectarray element, some simplifications may be considered. Due to the reflectarray unit cells are modelled as an ideal phase shifter, the module of the reflection coefficients is assumed to be 1, therefore no losses are considered (i.e. $|\rho_{xx}^m| = |\rho_{yy}^m| = 1$). Additionally, there is no cross-polarization influence ($\rho_{xy}^m = \rho_{yx}^m = 0$). Now, the coefficient reflection matrix is simplified to

$$\mathbf{R}^m = \begin{pmatrix} e^{j\phi_{xx}^m} & 0 \\ 0 & e^{j\phi_{yy}^m} \end{pmatrix} \quad (3)$$

where ϕ_{xx}^m and ϕ_{yy}^m are the phase of the direct reflection coefficients of the element, which are used as degrees of freedom in the synthesis of the near-field radiated by the reflectarray.

Once the field at the aperture is computed, the near-field \vec{E}_{NF} can be obtained by forward propagation (FP). In this work, this propagation model is based on a principle of superposition, where each element of the reflectarray is an unit radiation element modelled as a small aperture antenna, instead of a punctual isotropic source. Then, the near-field radiated by the reflectarray at one point of the space is computed

as the sum of all the far-field contributions radiated by each reflectarray cell:

$$\vec{E}_{NF}(\vec{r}) = \sum_{m=1}^{Nelem} \vec{E}_{FF}^m(\vec{r}) \quad (4)$$

where \vec{r} is the position vector where the near-field of the reflectarray is computed; $Nelem$ is the total number of unit radiation elements; and $\vec{E}_{FF}^m(\vec{r})$ is the far-field radiated by the m -element at \vec{r} . This far-field contribution of the m element can be computed using the Second Principle of Equivalent for planar aperture antennas, which uses the field at the aperture \vec{E}_{AP} of (2) [24].

Typically, the computed near-field (\vec{E}_{NF}) does not satisfies the specifications, therefore the forward projector (\mathcal{F}) projects it onto a new radiated field (\vec{E}_{NF}) that fulfills the requirements. However, this does not necessarily means having a radiated field that can be radiated by the antenna, since the constraints are only imposed in the radiated field but not in the antenna optics. The backward projector (\mathcal{B}) is more complex than the forward and is divided into several steps. Firstly, backward propagation (BP) allows to compute the source of \vec{E}_{NF} , thus the field at the aperture \vec{E}_{AP} is calculated. Reminding that the field at the aperture depends on the element response (see (2)), it is not ensured that \vec{E}_{AP} can be obtained with the proposed antenna. Hence, new constraints (\mathcal{A}) have to be imposed on the antenna geometry in order to obtain a achievable field at the aperture (\vec{E}_{AP}). Although the forward propagation of this new field is not \vec{E}_{NF} , the near-field obtained is closer to the requirements than the starting point, and additionally it is guaranteed that is achievable by the antenna optics. Doing this process iteratively, it may be reached a solution that satisfies both geometry and radiated field conditions.

B. Generalized Intersection Approach

In the classic implementation, the hardest step to deal with is the backward projector, particularly the need to find a proper backward propagation definition. In order to avoid it, there is an alternative that proposes the use of an optimization algorithm instead [25]. In this present case, the Levenberg-Marquardt Algorithm (LMA) has been chosen to be integrated inside the Intersection Approach as Fig. 3 shows. This algorithm is used to find \vec{E}_{NF}^{i+1} in \mathcal{R} closer to \vec{E}_{NF} than \vec{E}_{NF} .

Let us suppose a field at the aperture \vec{E}_{AP} radiated by the antenna. Then, the previous forward propagation (FP) is applied and a generated field within the near-field region is obtained (\vec{E}_{NF} belonging to \mathcal{R}). It is likely that on the first iteration this field does not fulfill the requirements, therefore the forward projector (\mathcal{F}) will project it onto a desired field (\vec{E}_{NF}), which belongs to the set \mathcal{M} . This projector is defined to ensure that:

$$T_{lower} \leq \vec{E}_{NF} \leq T_{upper} \quad (5)$$

where \vec{E}_{NF} is the constrained field that belongs to \mathcal{M} ; T_{lower} and T_{upper} are the lower and upper specification boundaries respectively.

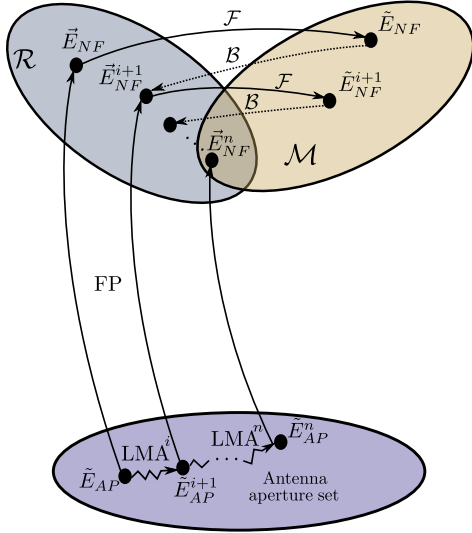


Fig. 3: Sketch of the generalized Intersection Approach and its iterative process.

Ultimately, this projector trims the radiated field according to certain specifications, which are generally given in form of templates. Hence, \tilde{E}_{NF} can be computed as

$$\tilde{E}_{NF}(\vec{r}) = \begin{cases} T_{\text{upper}}(\vec{r}), & \text{if } \vec{E}_{NF}(\vec{r}) \geq T_{\text{upper}}(\vec{r}) \\ T_{\text{lower}}(\vec{r}), & \text{if } \vec{E}_{NF}(\vec{r}) \leq T_{\text{lower}}(\vec{r}) \\ \vec{E}_{NF}(\vec{r}), & \text{otherwise} \end{cases} \quad (6)$$

To apply the optimization algorithm LMA, the generalized Intersection Approach defines a functional d which evaluates the distances from one point of \mathcal{R} to another of \mathcal{M} , thus the distance from \vec{E}_{NF} to \tilde{E}_{NF} (see Fig. 3). This functional is based on the Euclidean distance definition but, it should be kept in mind that each element of those sets has to be expressed in terms of magnitude and phase. Therefore, the functional should be considered both components independently.

$$d = d_M + d_P = \int_{\Omega} w_M \left(\left| |\tilde{E}_{NF}|^2 - |\vec{E}_{NF}^{\text{LMA}}|^2 \right| \right) d\Omega + \int_{\Omega} w_P \left(\left| \angle \tilde{E}_{NF} - \angle \vec{E}_{NF}^{\text{LMA}} \right| \right) d\Omega \quad (7)$$

where Ω is the volume where the near-field is computed; and w_M and w_P are weight functions. If this volume is discretized in N_z planes along \hat{z} with N_{xy} points each one, this functional can be expressed as

$$d = \sum_l^{N_z} \left[\sum_j^{N_{xy}} w_M \left(\left| |\tilde{E}_{NF,j}|^2 - |\vec{E}_{NF,j}^{\text{LMA}}|^2 \right| \right) + \sum_j^{N_{xy}} w_P \left(\left| \angle \tilde{E}_{NF,j} - \angle \vec{E}_{NF,j}^{\text{LMA}} \right| \right) \right] \Delta_{x,j} \Delta_{y,j} \quad (8)$$

where the subscript l indicates the plane that is evaluated and j the (x, y) point where the distance is computed; and $\Delta_{x,j}$ and $\Delta_{y,j}$ are the step of the plane discretization. $\vec{E}_{NF}^{\text{LMA}}$ is the field used by the LMA to evaluate d , which is related with the field at the aperture as $\text{FP}(\vec{E}_{AP}^{\text{LMA}})$, being the degree of

freedom the phase distribution of the reflection coefficients on the reflectarray surface (ϕ_{xx} or ϕ_{yy}).

Note that, the goal of the LMA is only to reduce d in each iteration of the generalized Intersection Approach, but not reach a minimum of this distance, thus only few iterations are needed [25]. The starting point of the LMA is the near-field of the iteration i of the generalized Intersection Approach (\vec{E}_{NF}^i) and provides the near-field of the iteration $i+1$ (\vec{E}_{NF}^{i+1}), closer to \tilde{E}_{NF} . After several iterations of generalized Intersection Approach, an intersection between both sets may be found, \mathcal{M} and \mathcal{R} , obtaining a near-field within the constraints and feasible by the antenna. If this intersection is not possible, at least to obtain a field \vec{E}_{NF} with the least distance to \tilde{E}_{NF} .

Due to the LMA is a gradient-based algorithm, the differential contributions technique (DFC) [26] can be applied. This notably speeds up the computation of the functional gradient reaching computing times similar to analytical derivatives, whenever are available [27].

III. REFLECTARRAY DEFINITION

The proposed antenna to demonstrate its use as CATR probe is a squared reflectarray made up of 44×44 (1936) elements, which are distributed in a regular grid of a periodicity of $4.29 \times 4.29 \text{ mm}^2$ along the x - and y -axis. In this case, the reflectarray is feed using an offset configuration as shown in Fig. 1. The center phase of the feed is placed at $(x_f, y_f, z_f) = (-79.3, 0, 200) \text{ mm}$ considering the centre of the reflectarray as the origin of the system of coordinates. This feed is a pyramidal standard horn gain of 15 dBi gain (Narda v639), which generates an illumination taper of -15.80 dB at the edge of the reflectarray at a working frequency of 28 GHz.

On the other hand, the proposed unit cell to design the reflectarray is based on a central dipole and two lateral ones that are separated at a distance $S = 1.43 \text{ mm}$ from the central dipole as Fig. 4 depicts. The dipoles work in linear polarization and are oriented according to the x -axis of the reflectarray. The width of the three dipoles is $W = 0.5 \text{ mm}$ whilst the lateral dipoles lengths (L_1) are a function of the central length L_2 as $L_1 = 0.7L_2$. The dipoles are printed on the same size of a 0.762 mm thickness (h) Duclad 880 substrate ($\epsilon_r = 2.3, \tan \delta = 0.005$).

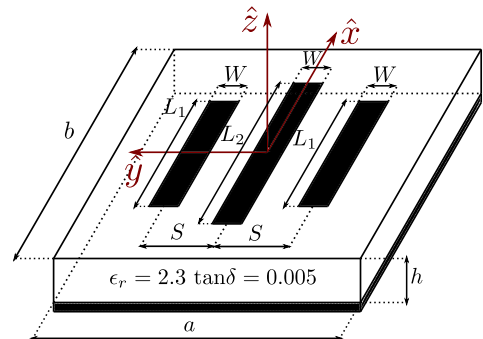


Fig. 4: Reflectarray element based on three parallel dipoles for a single polarization.

The phase responses of the cell are obtained by the variation of the length L_2 . In Fig. 5 both amplitude and phase response

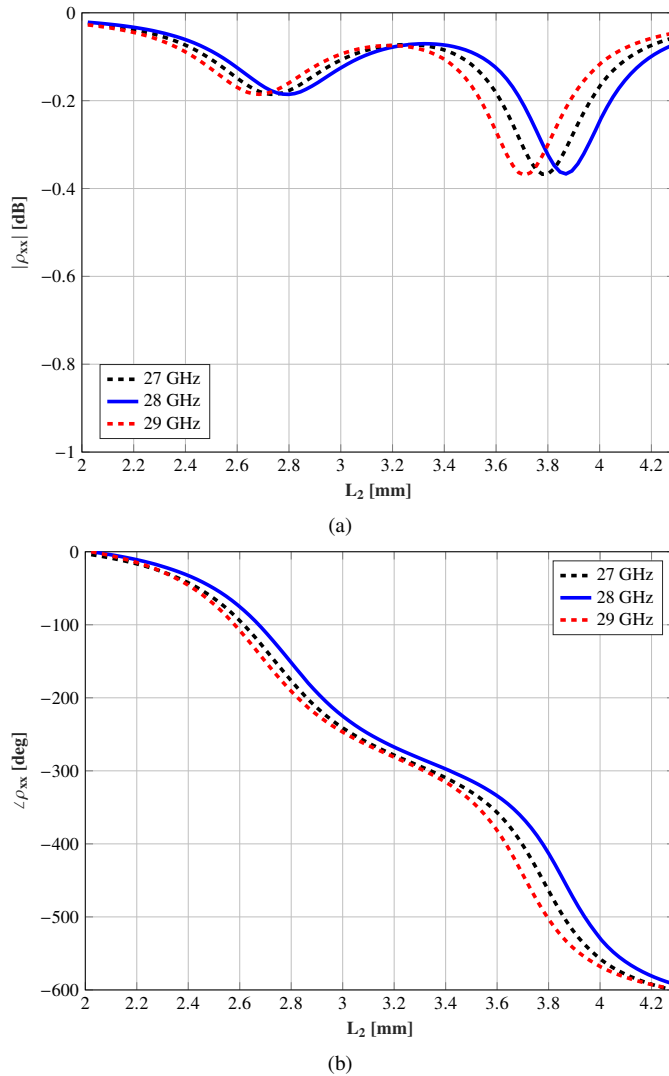


Fig. 5: Reflectarray cell characterization in x-pol versus L_2 (length of the central dipole) for incident (a) amplitude (b) phase.

are shown for normal incidence, obtaining a phase-shift larger than 360° . In addition, the studied range presents a soft slope, which helps to minimize the possible phase-shift errors due to the manufacturing tolerances. The amplitude in the worst case is lower than -0.40 dB (> 0.91 of reflection) and this cell response is stable within a 2 GHz bandwidth regarding the central frequency. The angular stability of the cell response has been validated through simulations.

Then, a reflectarray is defined to point at \hat{z}_a direction with an angle $\theta_0 = 20^\circ$ that generates an equivalent aperture (D) equivalent to

$$D = D_x \times D_y = 188.76 \text{ mm} \cdot \cos \theta_0 \times 188.76 \text{ mm} = 177.36 \times 188.76 \text{ mm}^2 \quad (9)$$

The quiet zone is evaluated on a perpendicular plane to \hat{z}_a direction at 500 mm (46.66λ) from the centre of the reflectarray, which provides a very compact structure since the far-field region starts at 12.52 m (1170.40λ). The quiet zone specifications are defined in a circular area of diameter

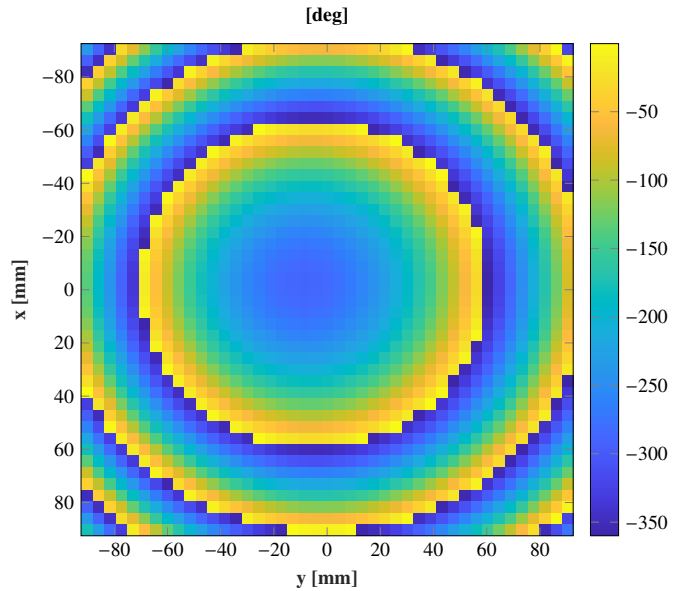


Fig. 6: Initial phase distribution [deg] of a far-field focused reflectarray at 28 GHz.

100 mm (9.33λ), more than the 56% and 53% of the antenna aperture width in the x and y axis, respectively. The maximum ripple within this area is 1 dB and 10° in amplitude and phase respectively, thus the theoretical quiet zone definition.

IV. NEAR-FIELD SYNTHESIS AND DESIGN BOTH AMPLITUDE AND PHASE CONSTRAINTS

A. Starting point

Considering the geometry previously defined, the starting phase distribution of the reflection coefficients (ρ_{xx}) selected is that defined for a far-field focused reflectarray radiating a pencil beam in a pointing direction $(\theta_0, \phi_0) = (20^\circ, 0^\circ)$. This phase distribution can be analytically computed as

$$\phi_r(x_m, y_n) = -k_0 x_i \sin \theta_0 - \phi_{inc}(x_m, y_n) \quad (10)$$

where ϕ_{inc} is the incident field phase provided by the feed at the (m, n) th element; and k_0 is the vacuum wavenumber. Fig. 6 shows the initial phase distribution computed using (10).

The quiet zone obtained by this phase distribution is shown in Fig. 7 for both amplitude and phase, additionally the quiet zone boundaries are represented using the solid red line. Due to the near-field is collimated in the direction where the quiet zone is placed, the phase of this field behaves as almost flat, specially at the $x = 0$. The offset cut ($y = 0$) increases the ripple because of the non-symmetry, even so, the maximum peak-to-peak ripple in the whole area is 22° . Conversely, the amplitude has a worse behaviour considering the ripple specifications. According to (2), the reflected field depends on the field provided by the feed, therefore if the field at the reflectarray surface has a high amplitude taper, the quiet zone will be affected increasing the variation along the zone more than 8 dB as Fig. 7a shows.

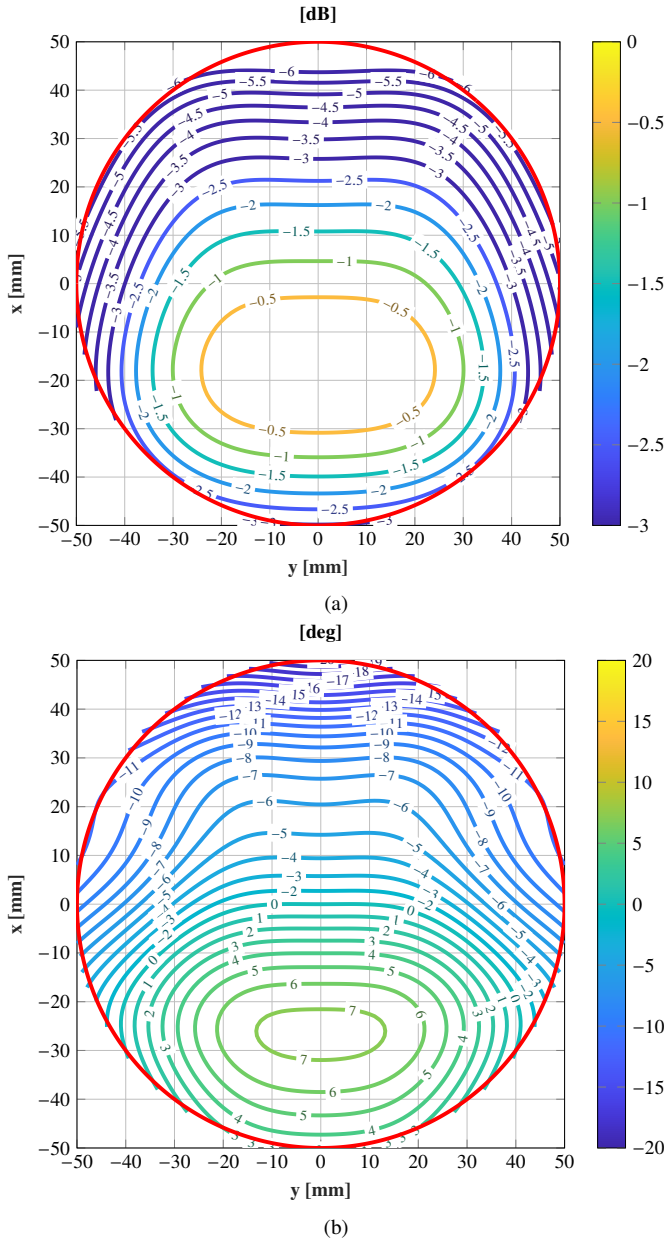


Fig. 7: Quiet zone for the starting point. (a) Normalized amplitude (dB) to the maximum. (b) Normalized phase (deg) to the value at the centre of the zone.

B. Synthesis results

The optimization process has been divided into a multi-stage strategy, particularly a total of 8 stages were needed until reaching the final solution. Starting from 1.5 dB and 20° of amplitude and phase ripple, the specifications have been tightened once the previous stage requirement had been fulfilled. The 1 dB and 10° ripple has been virtually reached after 2938 iterations of the generalized Intersection Approach and 3 LMA iterations in each one. The phase distribution of the reflectarray elements obtained is shown in Fig. 8. The phase variation along the reflectarray surface is smooth enough for a proper design.

The synthesised quiet zone is shown in Fig. 9, while Table

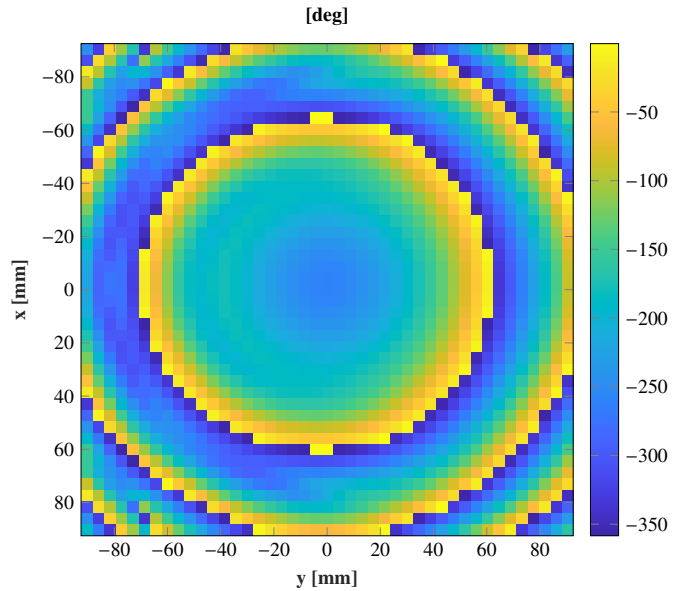


Fig. 8: Optimized phase distribution obtained after the optimization process.

I outlines a comparison of maximum ripples and specification compliance before and after the optimization. Both amplitude and phase show a significant improvement, highlighting the increment from a 25% to a nearly 90% of compliance in the amplitude and a ripple reduction of 7 dB. Despite having a markedly better starting point on the phase, the optimized one reduces its ripple to 4.30° in the whole quiet zone.

Note that the main cuts ($x = 0$ and $y = 0$) are of a particular interest since they represent the largest dimension of the quiet zone because of its circular shape, specially the cut $y = 0$ that is directly affected by the feed position. After the synthesis this cut has been significantly enlarged with an increase of a 262% and 303% in the amplitude and phase quiet zone size, respectively. The cut $x = 0$ is also enlarged in a 209% and 135% in amplitude and phase respectively. Hence, the current quiet zone has the same size in the main cuts.

Table I: Evaluation of the maximum ripple and the specification compliance in the quiet zone and its main cuts for the starting and optimized point.

		Starting point		Optimized point	
		Max. ripple	Compliance (%)	Max. ripple	Compliance (%)
Quiet Zone	Ampl. (dB)	-8.01	25.25	-1.33	89.42
	Phase ($^\circ$)	26.82	46.01	4.30	100
Main Cuts	Ampl. (dB)	-8.01	38.83	-1.10	83.49
	Phase ($^\circ$)	26.82	39.80	4.30	100

C. Reflectarray design

Once the phase distribution on the reflectarray surface has been obtained, the elements of the reflectarray must be designed. In the designing process, the sizes of the printed

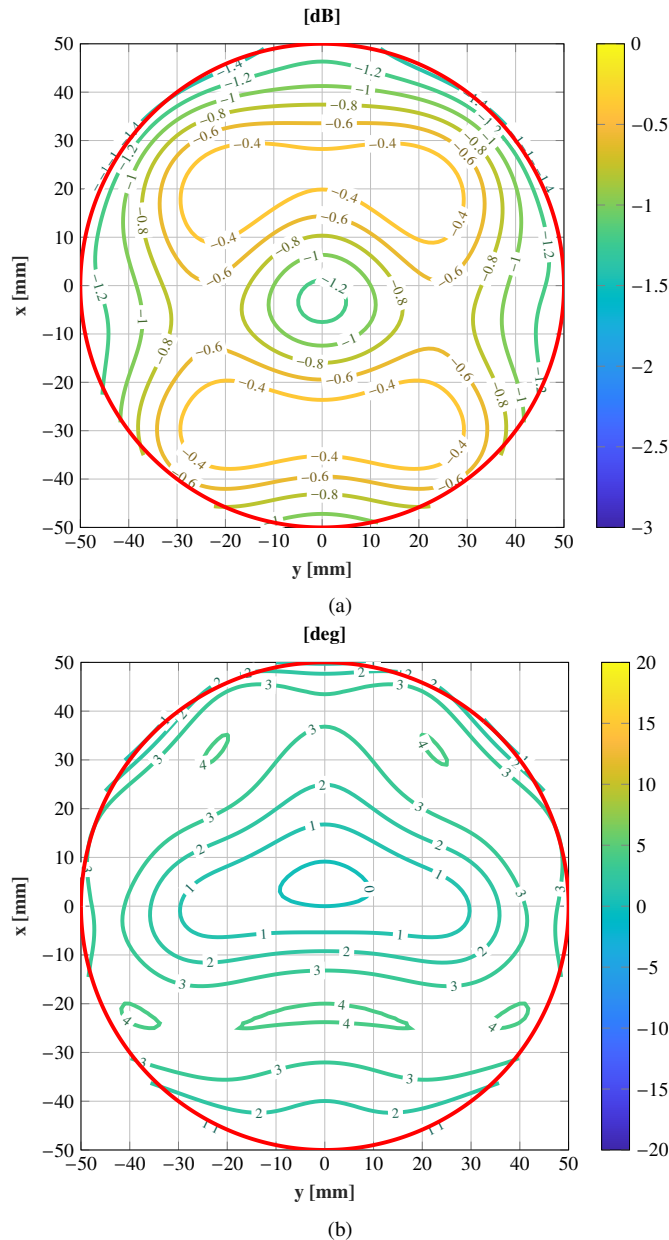


Fig. 9: Optimized quiet zone. (a) Normalized amplitude (dB) to the maximum. (b) Normalized phase (deg) to the value at the centre of the zone.

dipoles on the surface are adjusted to produce the required phase-shift. In this case, the process is carried out element by element, considering local periodic environment and, the real angle of incidence for each cell. A zero routing [23] is applied to obtain the length L_2 , allowing to match the required phase response of the cell obtained through a home made software based on Method of Moments with local periodicity (LP-MoM) [28] and the synthesized phase in the previous step. The output of the process is the layout of the 44×44 element reflectarray with a maximum error in the response of 0.1° for an individual cell.

The near-field radiated by the designed reflectarray has been computed in order to evaluate the performances of the quiet

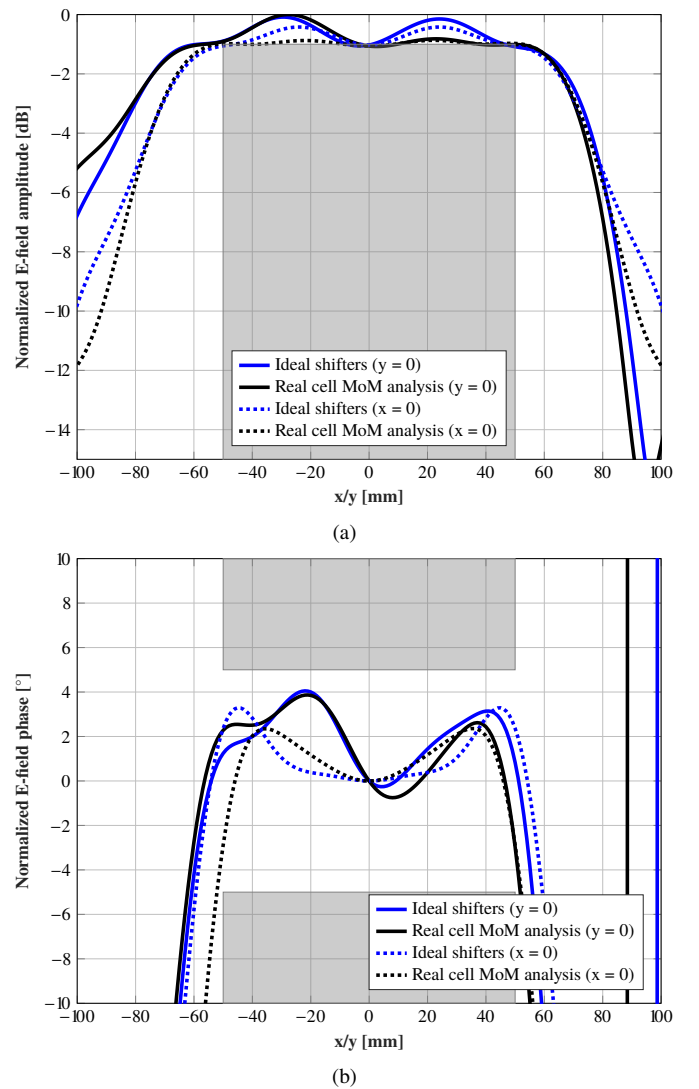


Fig. 10: Main cuts comparison between the synthesis results and the MoM analysis. (a) Normalized amplitude (dB) to the maximum. (b) Normalized phase (deg) to the value at the centre of the zone.

zone and compare them with the requirements. The resulting quiet zone are shown in Fig. 10, where slight differences can be appreciated, mainly as a consequence of the amplitude losses of the cell that are not considered in the phase-only synthesis, where the reflectarray elements are modelled as ideal phase-shifters. However, MoM results clearly satisfy the specifications within the desired area, showing a suitable quiet zone and validating the reflectarray design.

V. EXPERIMENTAL VALIDATION

The squared reflectarray of 44×44 cells has been manufactured. In order to properly evaluate the quiet zone, the prototype is measured in the planar acquisition range at the University of Oviedo. The reflectarray is placed on an aluminium structure and tilted $\theta_0 = 20^\circ$ (see Fig. 11), thus the plane wherein the quiet zone can be found is parallel to the probe aperture (an open-ended Ka-band waveguide). Although

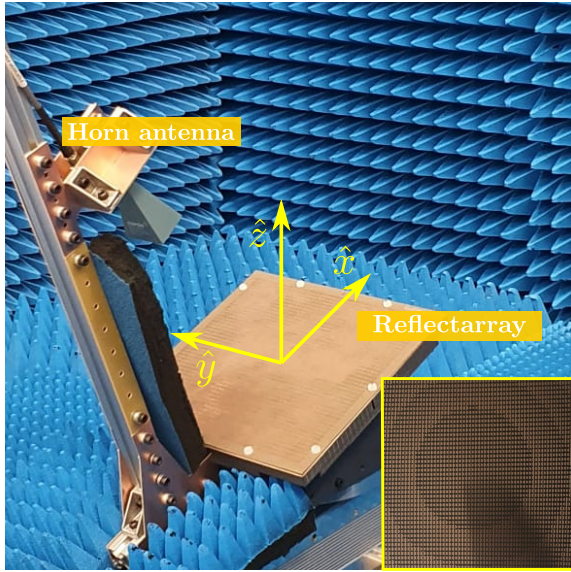


Fig. 11: Set-up at the planar acquisition range and zoom of the reflectarray.

the optimized plane corresponds to $z = 500$ mm, another three additional planes have been measured at a distance of 550, 600 and 650 mm. The nearby planes but after the optimized one are also affected though no specifications are imposed on them. Each plane is measured in a regular squared grid of 150×150 mm² that totally covers the quiet zone. In Fig. 12 the different measured main cuts of the quiet zone in amplitude (a) and phase (b) are shown and the whole area is shown in Fig. 13. All cases show a notably flattened in amplitude and, specially, in phase in most of the desired area as Table II outlines. The table gathers a detailed studio of the maximum peak-to-peak ripple and its percentage of compliance for different specifications levels. The plane at $z = 500$ mm has a maximum peak-to-peak ripple, evaluating the whole quiet zone, of 2.07 dB, Fig. 13a, and more than a 93% is within 1 to 1.5 dB peak-to-peak ripple. Main cuts show an amplitude taper lower than 1 dB and a maximum ripple of 1.63 dB in the worst case ($y = 0$). The maximum phase deviation is 15.33° and nearly the 90% of the total area has a peak-to-peak ripple lower than 10° (see Fig. 13e). The phase along its main cuts is particularly flat with a maximum ripple of 11° . The uniformity of this plane is extended to the measured volume. The plane $z = 550$ mm shows a maximum peak-to-peak ripple of 2.15 dB whilst a 91% of the area is within a 1.5 dB peak-to-peak, Fig. 13b. The amplitude taper at its main cuts is lower than 1 dB and the maximum ripple is 1.75 dB. Although the phase has a singular area that increases the maximum deviation to 19° , the quiet zone phase has a smooth variation, a 93% has a peak-to-peak ripple lower than 15° and a 84% within 10° , Fig. 13f. The amplitude at $z = 600$ mm has a similar behaviour to previous planes, having a maximum peak-to-peak ripple of 2.43 dB, noticing that practically the 90% of the total quiet zone is within a 1.5 dB ripple, Fig. 13c. The amplitude taper in both main cuts is lower than 1 dB and its maximum ripple is 1.69 dB. The

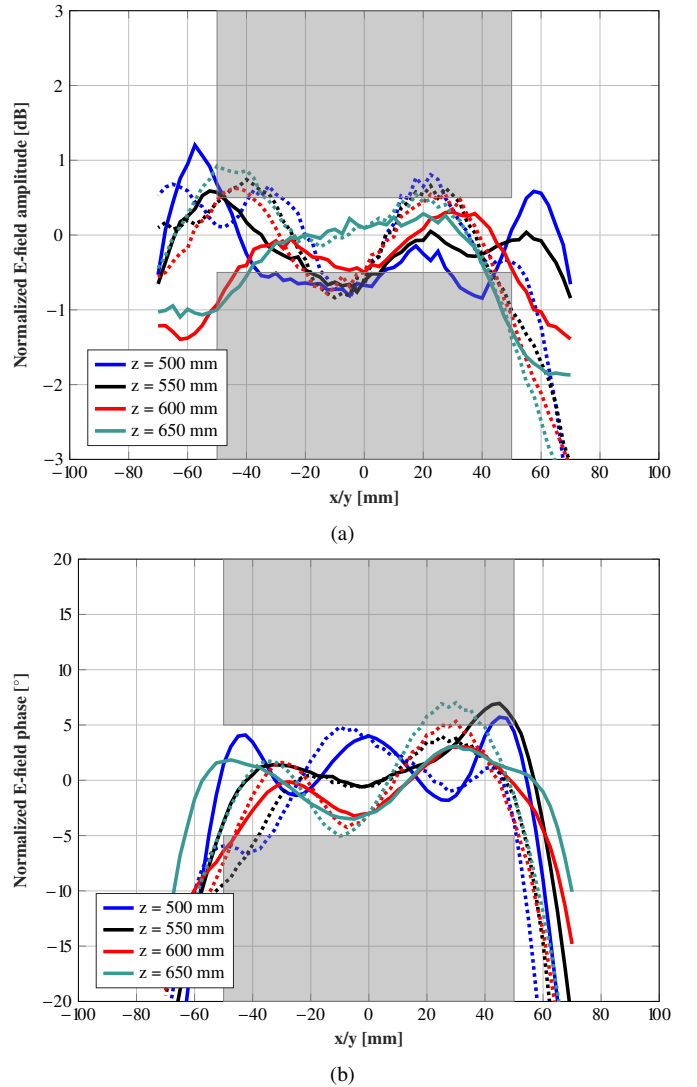


Fig. 12: Main cuts of the measurements at 28 GHz (a) Normalized amplitude (dB) to the mean value of the quiet zone. (b) Normalized phase (deg) to the value mean value of the zone (solid line) cut $y = 0$ (dotted line) cut $x = 0$.

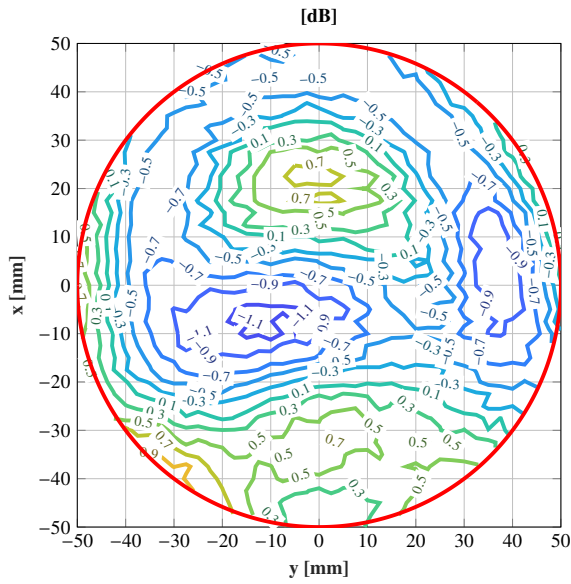
phase at this plane is markedly flat, the maximum deviation is close to the 15° of the plane $z = 500$ mm, and a maximum ripple of 10° in more than the 88% of the area, Fig. 13g. The plane $z = 650$ mm slightly increases the peak-to-peak ripple to 3 dB, and, a 83% of the quiet zone is within a 1.5 ripple. However, only the upper edge of the quiet zone is affected by this increase (see Fig. 13d). The central area remains with a very smooth variation close to 0.8 dB ripple. The amplitude taper in both main cuts is close to 1 dB, though the ripple is higher than other planes. The uniformity of the phase is undoubtedly smooth, nearly the 90% is under a 10° peak-to-peak ripple and the whole area within 15° , Fig. 13h.

VI. CONCLUSIONS

A reflectarray antenna made of cells based on three parallel dipoles is proposed to be used as a probe in a compact and portable CATR for 5G new radio devices measurements.

Table II: Evaluation of the maximum ripple and the specification compliance in the measured quiet zone and its main cuts.

Plane	Amplitude				Phase				
	Max. peak-to-peak (dB)	1 dB Compliance (%)	1.2 dB Compliance (%)	1.5 dB Compliance (%)	Max. deviation (°)	10° Compliance (%)	15° Compliance (%)	20° Compliance (%)	
Quiet zone	500 mm	-2.07	73.11	83.09	93.22	15.33	88.88	95.35	100
	550 mm	-2.15	71.05	81.34	91.16	19.93	84.23	93.67	97.18
	600 mm	-2.43	73.35	82.63	89.64	15.91	88.04	97.79	100
	650 mm	-3.02	63.44	71.28	83.01	13.19	88.49	100	100
Cut $y = 0$	500 mm	-1.63	63.41	75.06	92.68	11.58	82.90	100	100
	550 mm	-1.75	43.90	63.41	85.36	13.36	82.92	97.56	100
	600 mm	-1.69	58.53	78.04	92.68	12.70	90.24	100	100
	650 mm	-2.30	70.73	78.04	78.05	12.05	73.17	100	100



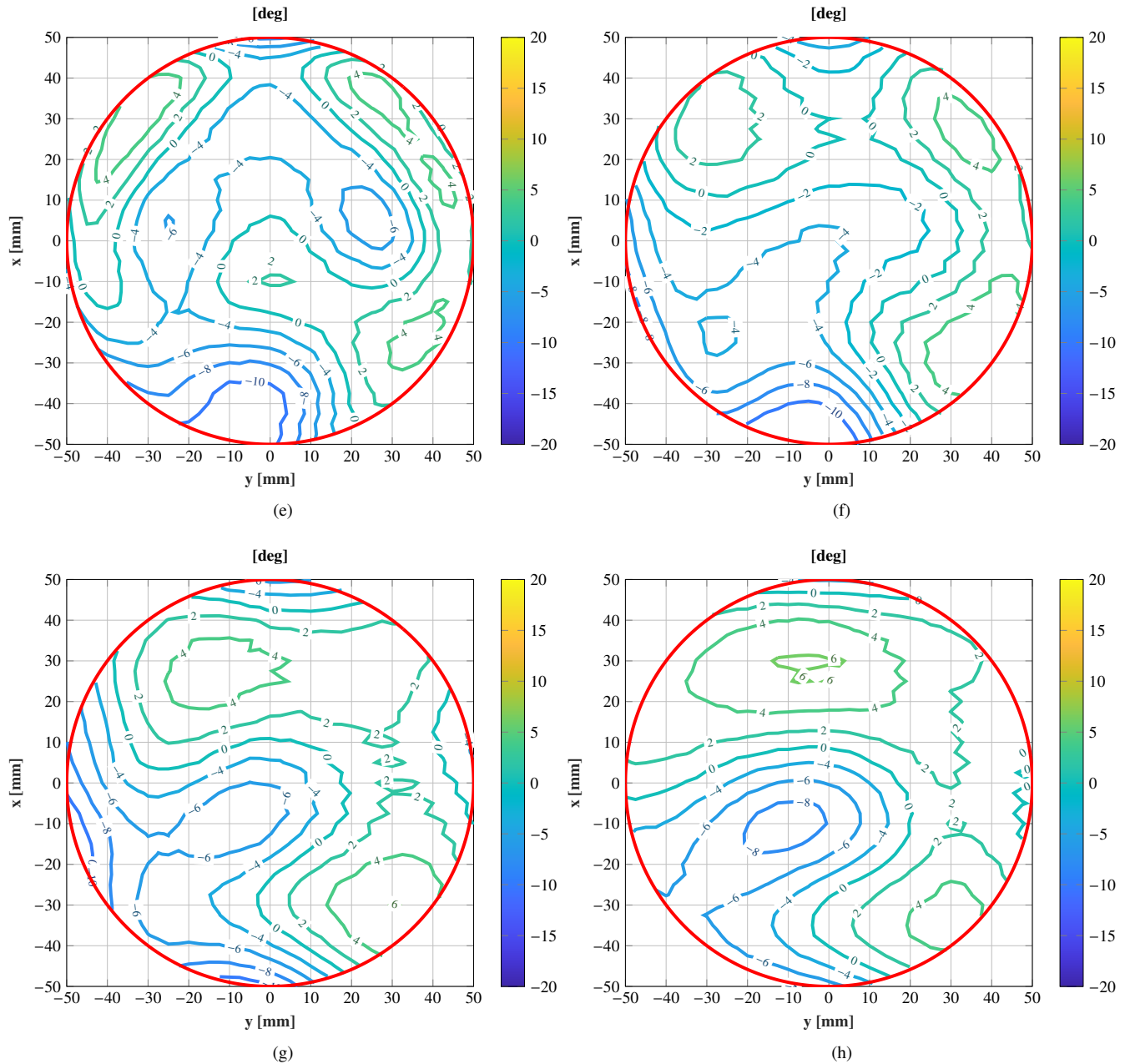


Fig. 13: Quiet zone measurements of the planes $z = 500$, $z = 550$, $z = 600$ and $z = 650$ mm at 28 GHz. (a) Normalized amplitude (dB) at $z = 500$ mm (b) Normalized amplitude (dB) at $z = 550$ mm (c) Normalized amplitude (dB) at $z = 600$ mm (d) Normalized amplitude (dB) at $z = 650$ mm (e) Normalized phase (deg) at $z = 500$ mm (f) Normalized phase (deg) at $z = 550$ mm (g) Normalized phase (deg) at $z = 600$ mm (h) Normalized phase (deg) at $z = 650$ mm. Both amplitude and phase are normalized to the mean value of each quiet zone.

Particularly, a reflectarray comprised by 44×44 elements with an equivalent aperture of 177.36×188.76 mm². This antenna should generate a quiet zone height of 100 mm (56% of D_x), a width of 100 mm (53% of D_y) and a depth of 150 mm starting at a distance of 500 mm (46.6λ) from the center of the antenna. Considering that the far-field starts at 12.54 m (1170.40λ), a quite compact structure is achieved at a working frequency of 28 GHz. A synthesis technique for the near-field radiated by a reflectarray using amplitude and phase constraints is presented

for the first time. In this case, the generalized Intersection Approach is employed to synthesize both amplitude and phase of the near-field. In order to avoid the use of a backward propagating model, the LMA is integrated inside the algorithm working as its backward propagation. The synthesis results have been obtained optimizing only the phase of the reflection coefficients of the reflectarray elements. The provided solution nearly reaches the 1 dB and 10° ripple specification in the desired circular area of 100 mm of diameter. Additionally,

the phase distribution along the reflectarray surface is smooth enough to perform a design. Particularly, a reflectarray cell based on three parallel dipoles has been chosen, allowing to cover more than 360° of the required phase-shift with a low level of losses. The design is analysed using a MoM software and a high agreement with synthesis results is obtained. Thus, it is manufactured and this prototype is measured in a planar range facility in order to evaluate the generated quiet zone. Four different planes have been measured, starting from the optimized plane to a total distance of 150 mm. Measurements show a high percentage of the quiet zone satisfying the 1 dB ripple in amplitude and the 10° in phase. A nearly 90% of the measured planes is within 1 to 1.5 dB peak-to-peak ripple and a taper lower than 1 dB, evaluating the main cuts of the quiet zone. The phase is significantly constant along the measured volume and almost a 90% is within 10° and the 100% within 15° . Hence, the prototype practically satisfies the theoretical quiet zone specifications in a quiet zone of size $100 \times 100 \times 150$ mm. In the light of these results, reflectarray antennas have demonstrated to be a potential candidate in the generation of quiet zones at high frequencies, taking the advantage of improving the quiet zone performances using the near-field technique presented in this work.

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