

Universidad de Oviedo Universidá d'Uviéu University of Oviedo



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FROM FALL DETECTION TO TIME SERIES CLUSTERING

A Computational Intelligence approach.

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- Previous research
- A reason for the change
- Fall detection
 - An introduction
 - Using wearables
 - Machine Learning developments
 - Current challenges
- TS balancing
 - Focusing on the type of TS problems
 - TS augmentation
- TS clustering
 - A review of the field
 - Current developments

FROM FALL DETECTION TO TIME SERIES CLUSTERING

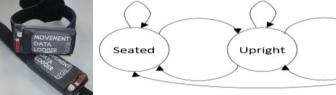
A Machine Learning

FROM FD TO TS

approach

Wearable sensors and illness and abnormalities detection

• Stroke movement detection [1,2]



Procedure: Boosting Fuzzy Rules **Input**:

a data set of size m; the number of rules to learn N

Output:

a rule base of size N

R=[]

for each rule r=1,...,N

run a GA

```
call AddOneRule for each individual
```

```
add the rule of minimum fitness value to R
```

```
for j=1,...,N
```

```
make all {\rm s}_k{}^j\!\!=\!\!0 but the maximum one {\rm s}_{q(j)}{}^j return R
```

Fig. 6 The Boosting Fuzzy Rules learning algorithm with the single winner inference.

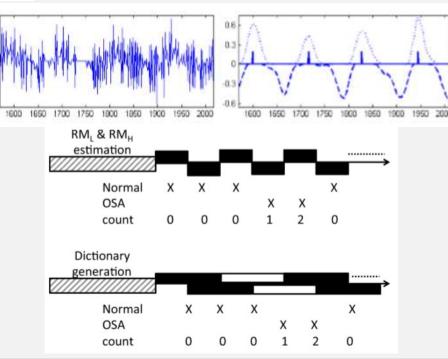
- Sleep apnea detection, SAX dictionaries [3]
 - 1. Data pre-processing

Walking

0.012

-0.012

- 2. Posture identification
- 3. Breath-cycle identification
- 4. Apnea identification



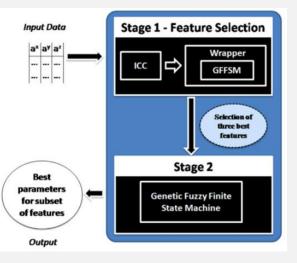


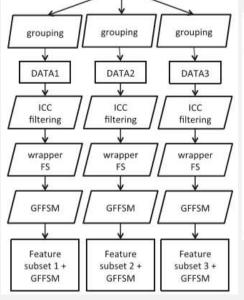
Wearable sensors and illness and abnormalities detection

- Tonic-Clonic Epilepsy seizure detection [4]
 - Finding the most interesting features that could be computed from a sliding window. A TS is represented with the most relevant features.
 - The main problem here was the availability of data.



- Is it possible to extract features and learn generalized models to identify abnormal movements?
- PCA and Local PCA have been found suitable, • Ts while LLE did not.





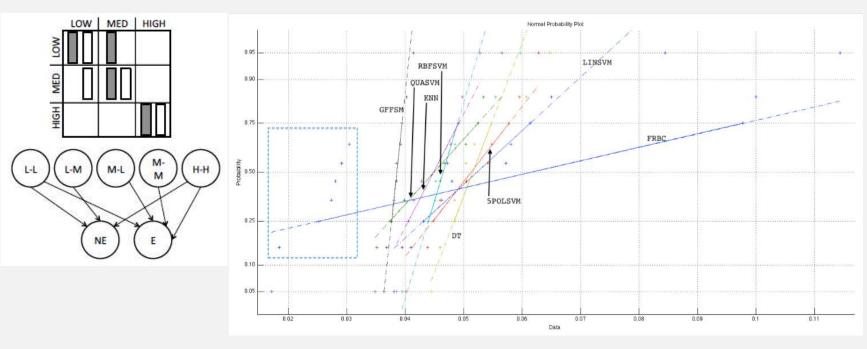
TS

Fold	PCA			LPCA				
	3KNN	5KNN	DT	3KNN	5KNN	DT		
1	0.9912	0.9916	0.9209	0.9591	0.9590	0.9373		
2	0.9848	0.9872	0.9468	0.9686	0.9669	0.9716		
3	0.9770	0.9783	0.9493	0.9269	0.9321	0.8840		
4	0.9932	0.9937	0.9712	0.9508	0.9522	0.9446		
5	0.9911	0.9894	0.9498	0.9644	0.9688	0.9516		
6	0.9757	0.9762	0.9708	0.9430	0.9487	0.9036		
7	0.9957	0.9950	0.9889	0.9752	0.9728	0.9642		
8	0.9572	0.9515	0.8823	0.8308	0.8240	0.8154		
9	0.9865	0.9862	0.9162	0.8894	0.8858	0.8262		
10	0.9900	0.9900	0.9625	0.9878	0.9880	0.9834		
Mean	0.9842	0.9839	0.9459	0.9396	0.9398	0.9182		
Mdn.	0.9882	0.9883	0.9495	0.9550	0.9556	0.9409		
Std.	0.0116	0.0129	0.0316	0.0472	0.0494	0.0594		



Wearable sensors and illness and abnormalities detection

- Tonic-Clonic Epilepsy seizure detection
 - Not so many calculations to avoid draining the battery \rightarrow sliding window and a restricted set of features.
 - Ant-Colony Optimization and Fuzzy Rule Based Systems [6]
 - Comparison of SVM, KNN, DT and Fuzzy Rule System [7]





Wearable sensors and illness and abnormalities detection

- Tonic-Clonic Epilepsy seizure detection
 - A wearable seizure epilepsy detection platform [8].

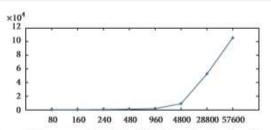


FIGURE 5: The exponential relationship between the data bunch size, x-axis, in KB, and the mean latency time, y-axis, in milliseconds, for the CC processing mode.

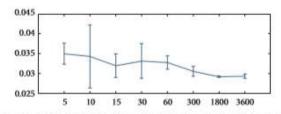
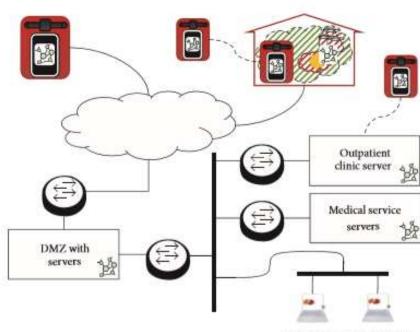


FIGURE 6: The relationship between the data bunch size and the ratio latency time versus the time between data bunch generation for the CC preprocessing mode. Some smaller sizes exhibit a wide spread; the higher the ratio, the narrower the variation in the performance.



Health service data analysis and modelling design





Get to know the problem with the elder

- Falls occur everyday: one of three elderly people suffer a fall [9].
- The sooner the detection the better.
- Confidence is all.
- The ergonomic factor.

Hey, is fall detection still a CHALLENGE???

A REASON FOR A CHANGE

sometimes life turns in unexpected whirls

FROM FD TO TS CLUSTERING

COMMERCIAL DEVICES

Video, sound, radar...



Sensifall, the smart floor detection system

Sensifall can automaticaly detect any activity, analyse it and inform the right people.

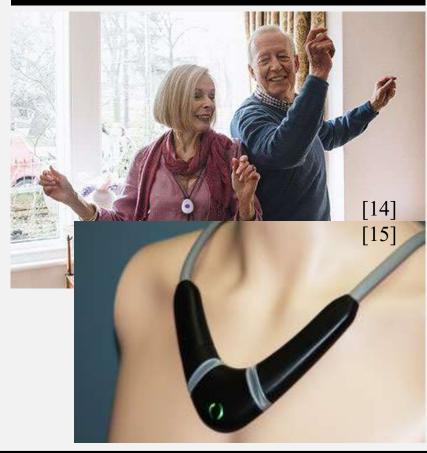
[13]



COMMERCIAL DEVICES

Personal emergency response systems (PERS) - Necklaces

Types of PERS



Characteristics

- False alarms: the price to pay.
- Access to health services 24/7 [16,17].
- Well, let's accept it: they are not nice to use... "That is a really neat feature at our age, instead of a necklace, says John Helmus, 76 [19].
- Confidence reinforcement.
- The person needs to be conscious and able to reach the button [9].
- 80% of older adults wearing a PERS did not use their alarm system to call for help after experiencing a fall [9].



COMMERCIAL DEVICES

Wearables and smartwatches



- Well-known trademarks are pursuing wearable fall detection systems.
- Apple Watch Series 4 [18]
 - Alarms when hard falls only.
 - If you are immobile → a Heatlh service call in 1 minute time.
 - If you keep moving, the call is delayed until a positive feedback.

"Apple says it studied the falls of 2,500 people of varying ages. Yet the company hasn't said how often it catches real falls or sets off false alarms.

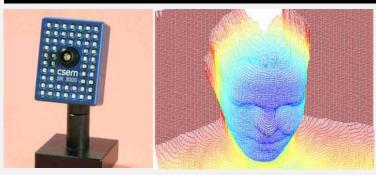
Apple's disclaimer says: "Apple Watch cannot detect all falls. The more physically active you are, the more likely you are to trigger Fall Detection due to high impact activity that can appear to be a fall."[19,20]





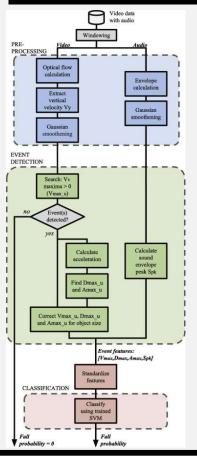
Video and motion sensor based solutions

3D Range cameras



- Video surveillance systems with/without sound.
- Simulated falls using stuntmen or volunteers.
- Participants are relatively young.
- Some studies analyse different types of fall events.
- All studies performed heuristic rules [23] or matching of specific patterns [24].
- Indoor only Privacy, Occlusions ...

Video and sound [25]

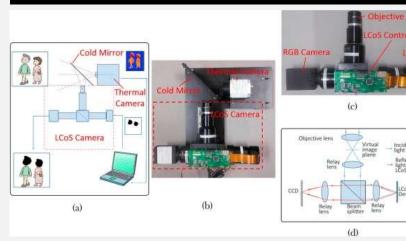


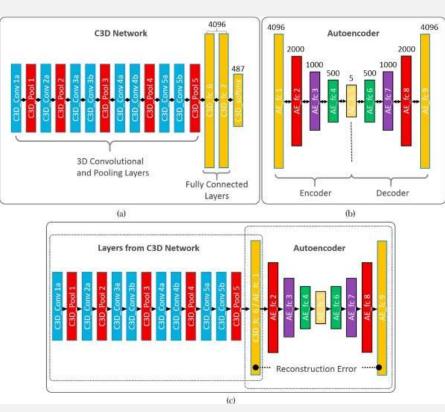
- Video and sound preprocessed independently.
- Event detection by determining the acceleration and speed of a subject PLUS a peak in the sound.
- Features are classified using a SVM.



Video and motion sensor based solutions

Video and Deep Learning [26]





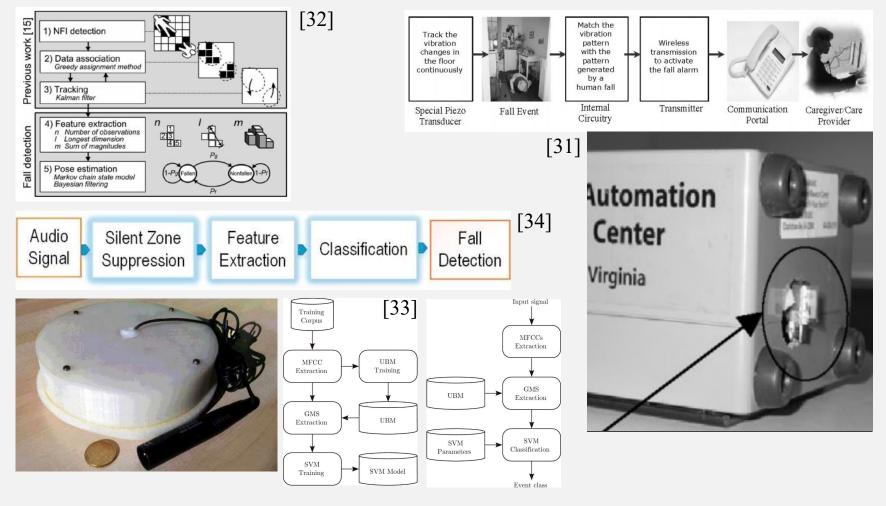
Motion sensors

- Kinect and LiDAR have been reported [27,28].
- Spatio-temporal fall event detection using DeepLearning might solve part of the problem [29].

Perhaps video approaches need to focus on normal behavior: any other activity might be anomalous [30].



Sound and floor solutions





Wearables

- Wearables makes the use easier
 The formed membration
- The focused population infers the sensor or sensors selection.
- The focused population infers the sensory location.

Why and where

Sensor type

- **3DACC**: [35,36,37,38,39, 41,42,43,44,45,46,47,48,49, 50,51,52,53,54,55,56,59]
- **Barometer**:[45,52]
- **Gyroscope**:[38,43,45,52,53]
- Electromyography:[60]
- Sensor fusing:[36], angle [58]

- 1. Record data using the sensory system.
- 2. Pre-process and feature extraction.
- 3. Learning a model.
- 4. Deployment.

General procedure

Modelling technique

- **SVM**: [42,44,45,49,50,51, 56]
- **KNN**: [42,49,50,51,54,57, 59]
- NN: [35,40,44,49]
- **Trees**: [38,42,51]
- **Rule Set**: [39,41,46,47,48,52, 53,55]
- Heuristics:[36,43]
- HMM

The **computation is run** on the device, on the edge or on the cloud.

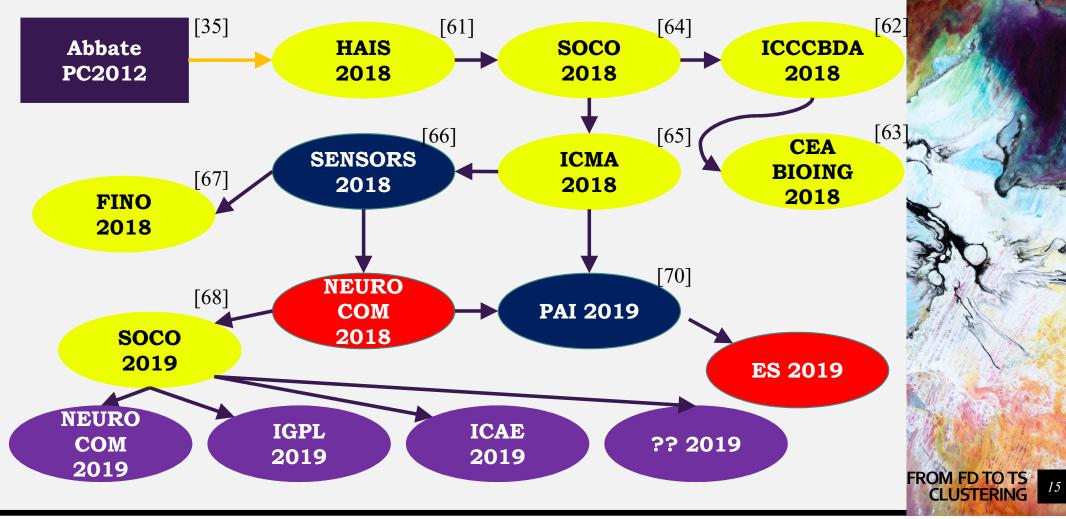
The **data come from** an ad-hoc dataset, a published dataset or a combination of both. Generalized Vs user-centered modelling.

Design and learning

Sensor location

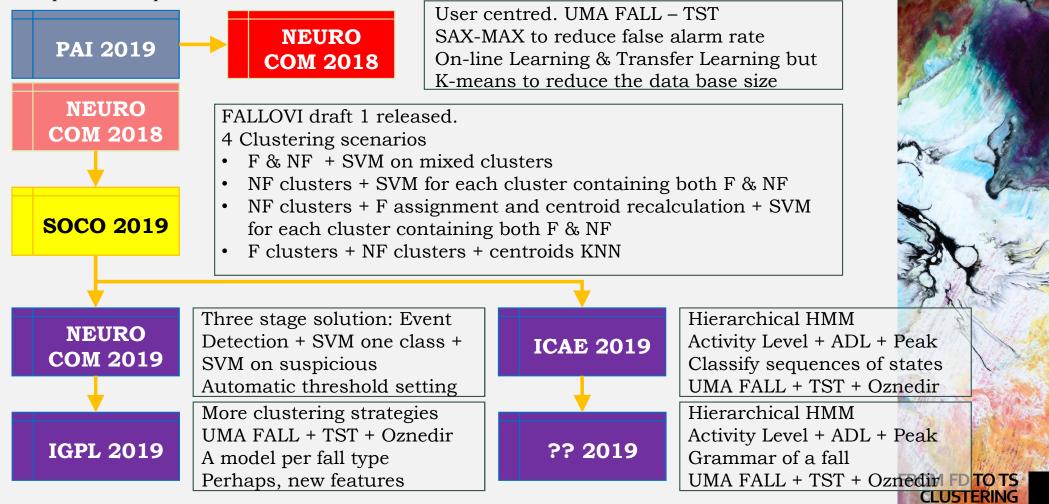
- Wrist: [36,37,39,40,41,42, 43,44,48,50,52,54,55,59]
- Waist: [35,38,45,46,47,53, 54,56,58]
- Thigh: [37,39,49,51,58]
- Other: chest [51], ankle [53]

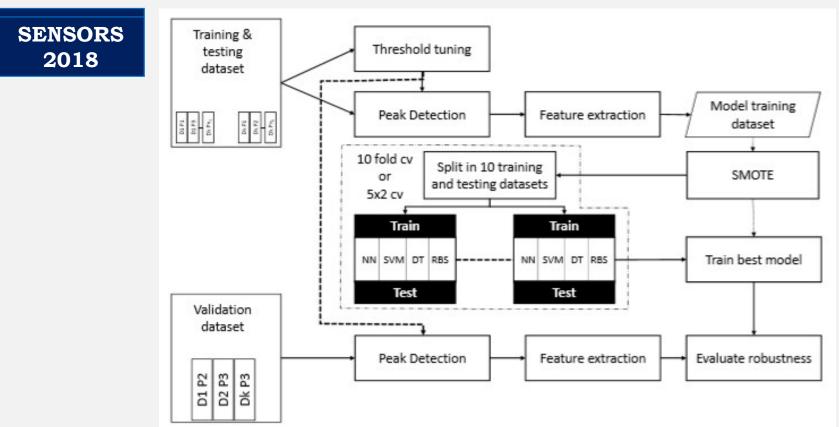




Abbate PC2012	Sensor on the waist Finite State Machine for Event Detection Feature extraction Neural Network	Highly imbalanced data Too many thresholds and timers Seems logical					
HAIS 2018	Sensor on the wrist → more challenging Finite State Machine for Event Detection Feature extraction but changing a bit Neural Network	Data Normalization SMOTE 60/40 to balance the classes UMA Fall 5x2 and 10-f cv					
SOCO 2018	Reducing the computational cost of model evaluation: C5.0 decision trees.	Model tuning: fog/cloud computing. Basic requirements for the design of a fall detection platform.					
	ICCCBDA 2018 CEA BIO 2018	Developed platform to deploy at a Senior Residence Hall in Burgos (Spain), belonging to the Health Care System.					
Analysis of the $5x2$ cv results \rightarrow poor generalization capabilities. The models can not cope with the whole solution \rightarrow new solutions are needed: centred design, ii) ensemble of classifiers, iii) divide and conquer: a model per formation capabilities.							

SENSORS 2018	More models Threshold an	ased cross validation. : NN, DT, RBS & NN. alysis and optimization. ed falls similar to real?	UMA Fall DaLIAC UNIOVI EP FARSEEIN	
FI	NO 2018	Participant-based 5x2 cv. DT (C5.0), NN, RBS, SVM. Ensemble basic voting.		
NEURO COM 2018	DaLIAC Esemble (vot	TST – UNIOVI EPILEPSY – ing &weighted): RBS, SVM, ndom Forest.	Ad-hoc data User centre	are far to be reliable. asets allow smooth results. ed solutions might be helpful. real falls are needed.
PAI 2018	_ <u>+</u>	: KNN and SAX-TFIDF Transfer learning :	UMA FALL Too many fa	sis on thresholds: 3 scenarios. – TST alse alarms but OL-TL SAX-TFIDF e best fall detection rate!







ISORS		1			IN						т			1 pro
	Fold	Acc	Кр	Se	Sp	Pr	G	Acc	Кр	Se	Sp	Pr	G	
018	1	0.9226	0.8440	0.9239	0.9211	0.9341	0.9290	0.8988	0.7936	0.9565	0.8290	0.8713	0.9129	The Car
	2	0.8810	0.7586	0.9130	0.8421	0.8750	0.8938	0.9286	0.8548	0.9674	0.8816	0.9082	0.9373	- Mana
	3	0.8810	0.7608	0.8696	0.8947	0.9091	0.8891	0.8333	0.6549	0.9674	0.6711	0.7807	0.8691	5
	4	0.8750	0.7468	0.9022	0.8421	0.8737	0.8878	0.9048	0.8065	0.9457	0.8553	0.8878	0.9163	
	5	0.8988	0.7969	0.8804	0.9211	0.9310	0.9054	0.7798	0.5540	0.8152	0.7368	0.7895	0.8022	
	6	0.8869	0.7725	0.8804	0.8947	0.9101	0.8952	0.8810	0.7603	0.8804	0.8816	0.9000	0.8902	Van
	7	0.8988	0.7965	0.8913	0.9079	0.9214	0.9062	0.8691	0.7405	0.7935	0.9605	0.9605	0.8730	The sea
	8	0.8810	0.7624	0.8370	0.9342	0.9390	0.8865	0.9226	0.8426	0.9674	0.8684	0.8990	0.9326	- Car
	9	0.8691	0.7351	0.8913	0.8421	0.8723	0.8818	0.8929	0.7838	0.9022	0.8816	0.9022	0.9022	*
	10	0.8750	0.7509	0.8261	0.9342	0.9383	0.8804	0.9167	0.8323	0.9130	0.9211	0.9333	0.9231	24
	mean	0.8869	0.7725	0.8815	0.8934	0.9104	0.8955	0.8827	0.7623	0.9109	0.8487	0.8832	0.8959	
	median	0.8810	0.7616	0.8859	0.9013	0.9157	0.8915	0.8958	0.7887	0.9294	0.8750	0.8995	0.9075	100
	std	0.0159	0.0320	0.0309	0.0380	0.0274	0.0147	0.0459	0.0935	0.0640	0.0856	0.0572	0.0403	5.30
	0.0107-024	1	2250	R	BS	10.83	7993	2.000	2945	SI	/M	1000	0000	To P
	Fold	Acc	Кр	Se	Sp	Pr	G	Acc	Кр	Se	Sp	Pr	G	SO.
	1	0.9107	0.8200	0.9130	0.9079	0.9231	0.9181	0.9345	0.8671	0.9674	0.8947	0.9175	0.9421	17
	2	0.8929	0.7847	0.8804	0.9079	0.9205	0.9002	0.8988	0.7955	0.9130	0.8816	0.9032	0.9081	/
	3	0.8869	0.7694	0.9457	0.8158	0.8614	0.9025	0.9107	0.8200	0.9130	0.9079	0.9231	0.9181	1
	4	0.8988	0.7936	0.9565	0.8290	0.8713	0.9129	0.9048	0.8069	0.9348	0.8684	0.8958	0.9151	A
	5	0.8691	0.7387	0.8261	0.9211	0.9268	0.8750	0.9107	0.8192	0.9348	0.8816	0.9053	0.9199	1261411
	6	0.9107	0.8196	0.9239	0.8947	0.9141	0.9189	0.8869	0.7730	0.8696	0.9079	0.9195	0.8942	112
	7	0.8631	0.7290	0.7826	0.9605	0.9600	0.8668	0.9405	0.8790	0.9787	0.8947	0.9184	0.9478	The second
	8	0.9286	0.8545	0.9783	0.8684	0.9000	0.9383	0.8988	0.7951	0.9239	0.8684	0.8947	0.9092	
	9	0.9107	0.8196	0.9239	0.8947	0.9140	0.9189	0.9107	0.8183	0.9565	0.8553	0.8889	0.9221	
	10	0.9286	0.8562	0.9239	0.9342	0.9444	0.9341	0.9167	0.8326	0.9022	0.9342	0.9432	0.9225	2 Parts
	mean	0.9000	0.7985	0.9054	0.8934	0.9135	0.9086	0.9113	0.8207	0.9294	0.8895	0.9110	0.9199	
	median	0.9048	0.8066	0.9239	0.9013	0.9172	0.9155	0.9107	0.8188	0.9294	0.8882	0.9114	0.9190	1.50 8
				0.0602	0.0449	0.0300	0.0232	0.0162	0.0324	0.0325	0.0234	0.0164	0.0157	

The publication path

SENSORS 2018

Not Fall

0

238

Not Fall

					Thresh	nold 2.5					
	Re	ference		Re	ference		Re	ference		Re	ference
NN	Fall	Not Fall	DT	Fall	Not Fall	RBS	Fall	Not Fall	SVM	Fall	Not Fall
Fall	10	47	Fall	10	20	Fall	10	42	Fall	8	18
Not Fall	2	250	Not Fall	2	277	Not Fall	2	245	Not Fall	4	279
					Thresh	old 3.0					
	Re	ference		Re	ference		Re	ference		Re	ference
NN	Fall	Not Fall	DT	Fall	Not Fall	RBS	Fall	Not Fall	SVM	Fall	Not Fall
Fall	12	52	Fall	11	18	Fall	11	29	Fall	10	12
Not Fall	0	245	Not Fall	1	279	Not Fall	1	268	Not Fall	2	285
					Threshol	d 3.09290					
	Re	ference		Re	ference		Re	ference		Re	ference
NN	Fall	Not Fall	DT	Fall	Not Fall	RBS	Fall	Not Fall	SVM	Fall	Not Fall
Fall	12	59	Fall	11	26	Fall	12	35	Fall	10	13

Not Fall

0

262

Not Fall

2

284

271

1



PAI 2019	normTSnormTH: normalized TS and norm KNN TF								normaliz TF-IDF		
	source	parID	TN	TP	\mathbf{FP}	\mathbf{FN}	TN	TP	FP	FN	
	TST	1	0	47	3	6	0	53	3	0	
	TST	2	0	57	0	3	0	60	0	0	
	TST	3	9	50	10	10	6	57	13	3	
	TST	4	0	60	4	0	0	43	4	17	
	TST	5	7	41	20	9	16	43	11	7	
	TST	6	0	55	0	0	0	55	0	0	
	TST	7	0	60	0	0	0	60	0	0	
	TST	8	0	63	3	4	0	66	3	1	
	TST	9	0	52	0	0	0	52	0	0	
	TST	10	0	57	7	3	0	52	7	8	
	TST	11	0	60	0	0	0	60	0	0	
	UMA Fall	1	14	85	16	10	16	93	14	2	
	UMA Fall	2	0	58	0	2	0	60	0	0	
	UMA Fall	3	20	76	23	14	33	73	10	17	
	UMA Fall	4	3	71	4	3	0	70	7	4	
	UMA Fall	9	0	82	3	11	0	93	3	0	
	UMA Fall	12	5	23	10	8	5	29	10	2	
	UMA Fall	15	2	41	12	4	2	45	12	0	
	UMA Fall	16	26	270	13	2	7	263	32	9	
	UMA Fall	17	0	57	16	6	3	54	13	9	



PAI 2019			norm	TSnor KN		norma	lized T	'S and	normaliz TF-IDI	zed thresholds
	source	parID	TN	\mathbf{TP}	\mathbf{FP}	\mathbf{FN}	TN	\mathbf{TP}	\mathbf{FP}	FN
	TST	1	57	47	3	13	57	53	3	7
	TST	2	60	57	0	3	60	60	0	0
	TST	3	50	50	10	10	47	57	13	3
	TST	4	56	60	4	0	56	43	4	17
	TST	5	40	41	20	19	49	43	11	17
	TST	6	60	55	0	5	60	55	0	5
	TST	7	60	60	0	0	60	60	0	0
	TST	8	57	56	3	4	57	59	3	1
	TST	9	60	52	0	8	60	52	0	8
	TST	10	53	57	7	3	53	52	7	8
	TST	11	60	60	0	0	60	60	0	0
	UMA Fall	1	74	85	16	15	76	93	14	7
	UMA Fall	2	90	58	0	2	90	60	0	0
	UMA Fall	3	67	76	23	14	80	73	10	17
	UMA Fall	4	96	71	4	9	93	70	7	10
	UMA Fall	9	87	81	3	9	87	90	3	0
	UMA Fall	12	100	23	10	17	100	29	10	11
	UMA Fall	15	38	41	12	9	38	45	12	5
	UMA Fall	16	307	270	13	10	293	263	27	17
	UMA Fall	17	74	57	16	33	77	54	13	36



The publication path

PAI 2019	normTSnormTH: normalized TS and normalized threshold TF-IDF TF-IDF + TL									
	source	parID	TN	\mathbf{TP}	\mathbf{FP}	FN	TN	TP	\mathbf{FP}	FN
	TST	1	0	53	3	0	0	53	3	0
	TST	2	0	60	0	0	0	56	0	4
	TST	3	9	55	10	5	0	60	19	0
	TST	4	0	35	4	25	0	60	4	0
	TST	5	17	35	10	15	0	50	27	0
	TST	6	0	55	0	0	0	55	0	0
	TST	7	0	60	0	0	0	60	0	0
	TST	8	0	61	3	6	0	67	3	0
	TST	9	0	52	0	0	0	52	0	0
	TST	10	0	41	7	19	0	60	7	0
	TST	11	0	60	0	0	0	60	0	0
	UMA Fall	1	24	52	6	43	0	95	30	0
	UMA Fall	2	0	60	0	0	0	60	0	0
	UMA Fall	3	41	35	2	55	0	90	43	0
	UMA Fall	4	2	64	5	10	0	74	7	0
	UMA Fall	9	0	81	3	12	0	93	3	0
	UMA Fall	12	7	13	8	18	0	31	15	0
	UMA Fall	15	8	28	6	17	2	45	12	0
	UMA Fall	16	35	217	4	55	0	272	39	0
	UMA Fall	17	12	37	4	26	0	63	16	0

FROM FD TO TS CLUSTERING

CHALLENGES IN DEVELOPMENT

- Gathering data from real falls
 - Presumably, the fall events will be unusual.
 - From the ML point of view, is like no real data is given
- Need to generate almost real TS
 - Considering the few TS from real falls
 - What is "an almost real TS"?
- Grouping or clustering TS
 - Applications in many fields apart from fall detection











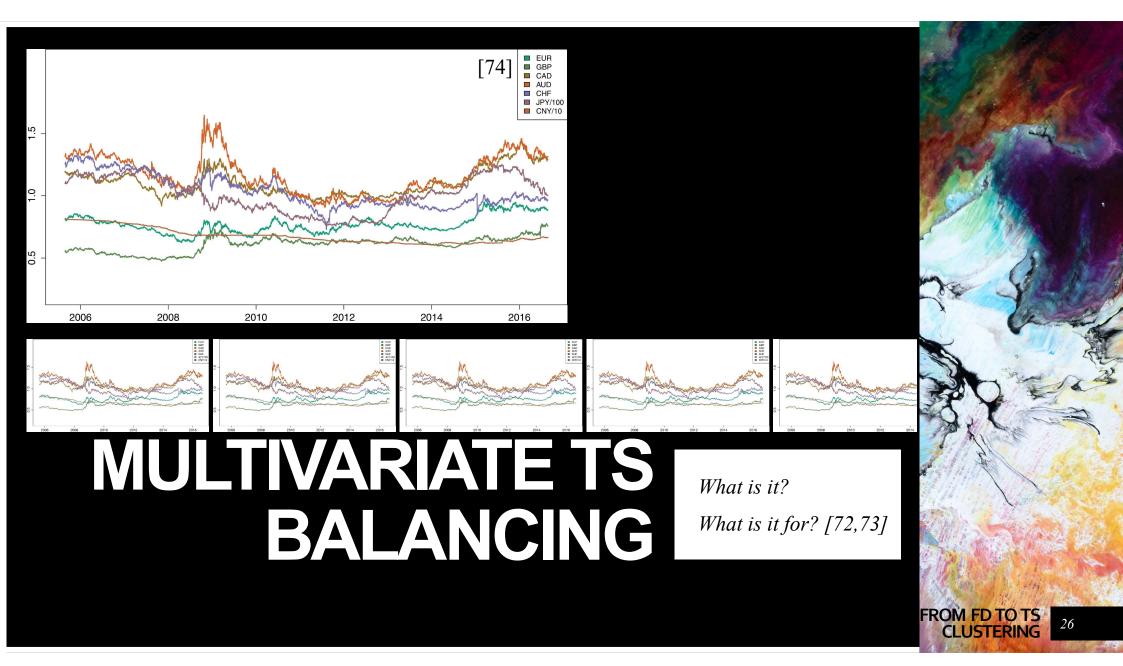






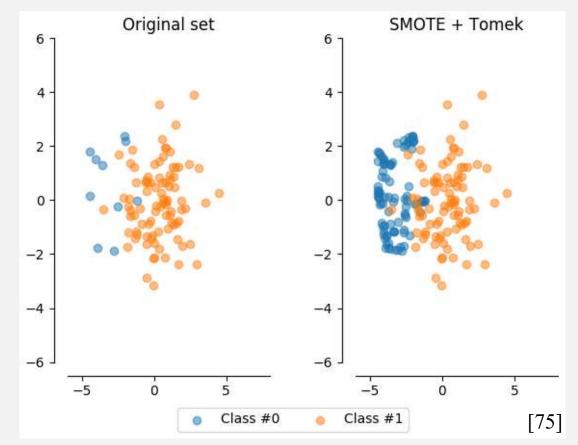






MULTIVATIATE TS BALANCING

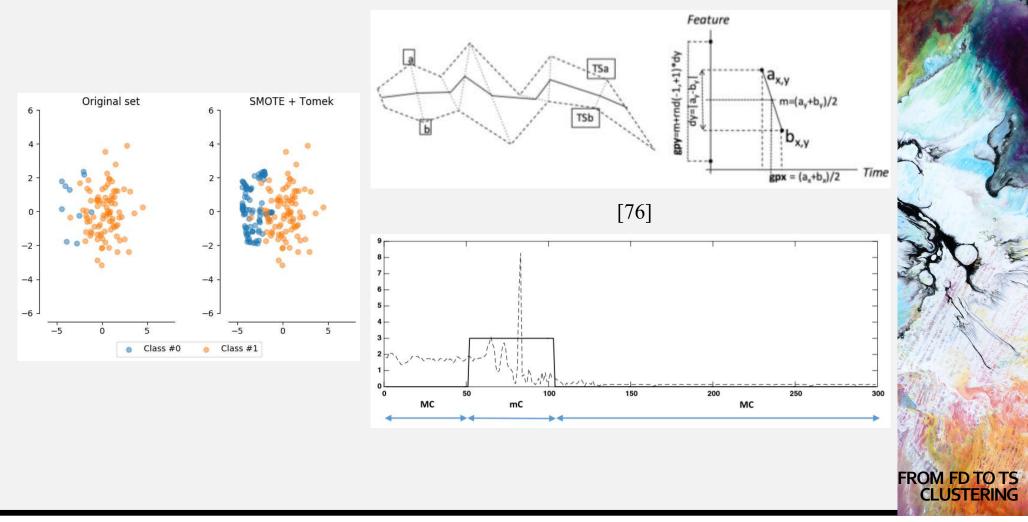
From SMOTE to TS SMOTE





MULTIVATIATE TS BALANCING

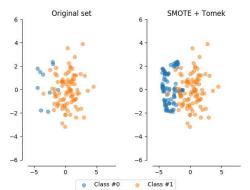
From SMOTE to TS SMOTE



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MULTIVATIATE TS BALANCING

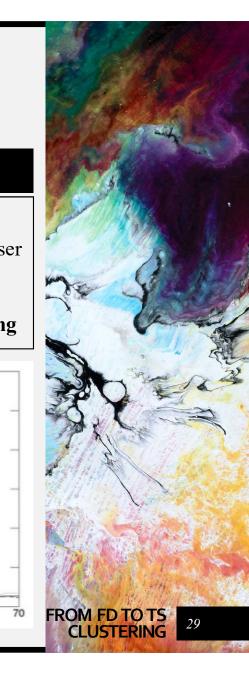
From SMOTE to TS SMOTE

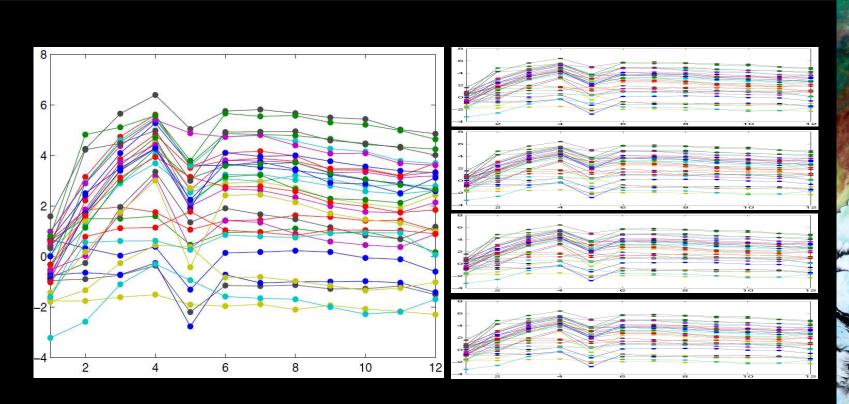


10

я

Original set SMOTE + Tomek	STILL PENDING	WI	HERE TO USE	
4 2 0 -2 -4 -6 -5 0 5 -5 -5 -5 -5 -5 -5 -5 -5 -5	 Outlier avoidance but needs a clear definition. Alternatives to the need of a guiding signal 	cer • Evalua	tection augmentation ntred tion of the ness of TS clus	
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10 20	30 40	50	60	70





MULTIVARIATE TS CLUSTERING

To group mutually dependent variables

FROM FD TO TS CLUSTERING

30

MULTIVARIATE TS CLUSTERING

TYPES OF mTS CLUSTER	WHOLE TS CLUSTERING
 Whole TS clustering Subsequence m-TS clustering Time point clustering 	 Model based: Gaussian Mixture Models [83], FE + SOM [84] Features based: PCA [79], discords [80], hash functions [81], stats & patterns [78] Shape based: HMM [82], Dynamic Time Warping [77] Hybridized and multi-step

A PRELIMINARY STUDY [85]

- The prediction error of a **Recurrent Neural Networks (RNN)** serves as a distance measurement to compare variables within an instance.
- **Transfer learning** from one instance to others helps in relaxing the computational costs.

CLUSTERING ISSUES

- **TS representation:** raw data
- **RNN error prediction** as distance measurement
- No prototyping needed



MULTIVARIATE TS CLUSTERING

A preliminary study [85]

Algorithm 1 Computing similarities between features in an example

- 1: procedure IN-EXAMPLE-SIMILARITY(TS^i , LoRNN) ▷ LoRNN list of pre-learnt RNNs, if available $sim \leftarrow$ zeroes matrix of size $n \times n$ 2: for each variable j in TS^i do 3: 4: $X_i^i \leftarrow \operatorname{normalize}(X_i^i)$ $RNN_i^i \leftarrow \text{Train-RNN}(X_i^i, \text{LoRNN}[j])$ 5: $LoRNN[j] \leftarrow RNN_{i}^{i}$ 6: $e_i^i \leftarrow \text{RMSE}(RNN_i^i, \text{test}(X_i^i))$ 7: for each variable k in TS^i , $k \neq j$ do 8: $X_{k}^{i} \leftarrow \operatorname{normalize}(X_{k}^{i})$ 9: $e_{ik}^{i} \leftarrow \text{RMSE}(RNN_{i}^{i}, \text{test}(X_{k}^{i}))$ 10: $sim[j,k] \leftarrow abs(\frac{e_{jk}^i - e_j^i}{e_j^i})$ 11: 12: end for 13: end for 14: return sim 15: end procedure 16: 17: procedure TRAIN-RNN (X_i^i, RNN) $\triangleright RNN$ is a RNN, if available if is.NULL(RNN) then 18: $RNN \leftarrow full train RNN$ for the train part of X_i^i 19: 20: else $RNN \leftarrow tune RNN$ for the train part of X_i^i 21: 22: end if return RNN 23: 24: end procedure
- Within-instance's similarities are converted to adjacency matrices
- if $sim(j,k) \le th_1$
 - For example i, x_j predicts x_k, denoted as k ≪_i j.
 - And $SIM_i[j, k] = 1$.
- Otherwise $SIM_i[j, k] = 0$.
- Adjacency matrices from each instance are aggregated: *SIM_{agg}*.
- Thresholding the SIM_{agg} matrix.
 - If $SIM_{agg}[j,k] \ge th_2$
 - $SIM_{final}[j,k] = 1$
 - $k \ll j$
 - Otherwise
 - $SIM_{final}[j,k] = 0$
- This final adjacency matrix allows to represent the dependency graph!



MULTIVARIATE TS CLUSTERING

A preliminary study [85]

A toy problem

- Indoor and outdoor temperatures in the weather station (TIN, TOUT).
- Horizontal and Vertical Irradiance reference measurement (HIR and VIR).
- The voltage at the weather station's battery (BV).
- The temperature of 4 photovoltaic panels linked to an inverter (T1 to T4).
- An In-panel Horizontal and Vertical Irradiance measurement (PHI, VHI).

T1 T4 T2 VIR

STILL PENDING

- Formal definition of all the stages
- Developing a more optimized and robust method.
- Extending the solution to cluster similar instances.
- Developing of suitable distances and efficiency measurements.
- Testing with a complete battery of m-TS datasets.



TIN

TOU



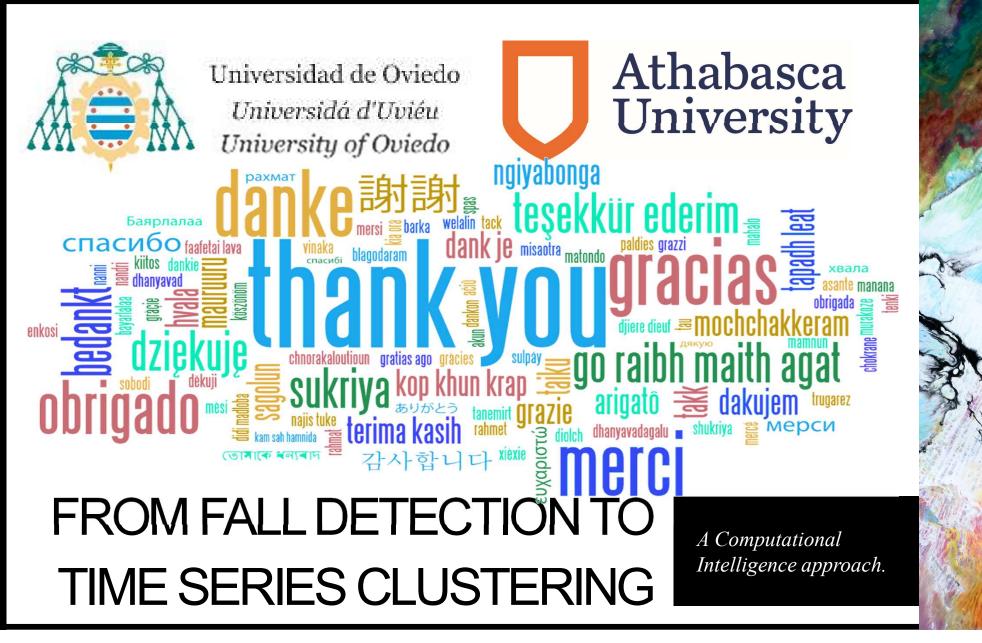
Mirko Fañez Víctor M. González Samad B, Khojasteh Enrique de la Cal Javier Sedano José R. Villar

THIS IS OUR TEAM!

Of course, I am not alone!







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