

Optimal discrete-time Prony series fitting method for viscoelastic materials

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Abstract

The most important characteristics of the behavior of viscoelastic materials are the time and temperature dependence of their properties. Viscoelastic models based on Prony series are usually used due to easy implementation in finite element analysis (FEA) codes. The experimental data are fitted to a Prony series using a user-convenience number of terms represented by two coefficients. The time coefficients τ_i are previously fixed in the time scale in order to determine the second parameters of the model. Usually, an homogeneous distribution in logarithmic-time scale is used for τ_i , which produces accurate fittings when a large number of terms in the Prony series are used as well as when the material presents a uniform sigmoidal viscoelastic curve along several decades of time. When short-time curves must be fitted or the relaxation curve shape is not so uniform distributed along time, the homogeneous distribution of time

1 coefficients could be a significant drawback since a large number of coefficients could
2 be needed or even a reasonable fitting with a Prony series model is not possible.

3 In this study, an optimized τ_i distributed method for fitting master curves of viscoelastic
4 materials based on Prony series model is proposed. The method is based on an
5 optimization algorithm strategy to allocate the time coefficients along the time scale in
6 order to obtain the best fit. The method is validated by using experimental data of
7 temporomandibular joint (TMJ) disc, which is a biological material that presents a short-
8 time and high relaxation rate viscoelastic curve. The results show that the method
9 improves significantly the fitting of the viscoelastic curves when compared with uniform
10 distributed time fittings.

11 Furthermore, the optimized coefficients are also used to obtain the complex moduli of
12 the material using an analytical conversion, which is compared with the experimental
13 complex moduli curves of the material.

14 **Keywords**

15 Viscoelastic; Prony series; Optimization; Relaxation; Soft materials; Viscoelastic
16 behaviour.

17

18 **1. Introduction**

19 The viscoelastic behaviour is present in a large number of materials used in both
20 engineering and biomechanical applications. The advantages of viscoelastic materials,
21 such as high-dissipative energy capacity (damping, noise and vibrations reduction or
22 shock impact absorber applications), are due to its mechanical properties which could
23 be say that are between the perfect solid and the perfect fluid (i.e. Newtonian)
24 behaviour (Ferry, 1980; Lakes, 1998; Tschoegl, 2012). Furthermore, the mechanical
25 properties of the viscoelastic materials are, at least, time and temperature dependent
26 (Christensen, 2003; Ferry, 1980). The advantages and mechanical properties of
27 viscoelastic materials can also be seen as drawbacks since, dealing with viscoelastic
28 behaviour, i.e. from a design or calculation point of view, implies taking into account
29 many variables that must be considered in the material characterization as well as in the

1 material model. Many materials, either as natural (wood or biological tissues) or artificial
2 processed (polymers, asphalt pavement or foams) presents viscoelastic behaviour so a
3 better understanding and characterization of these materials are needed. But not only
4 with the objective of improving designs and calculations even to having a better
5 understanding of these materials response, i.e. in biomechanical applications.

6 To characterize the viscoelastic behaviour, experimental tests are carried out in
7 rheometers or dynamic mechanical analysis (DMA) equipments. After the experimental
8 data is measured, i.e. the relaxation Young's modulus of the material, a viscoelastic
9 mathematical model is fitted to the experimental curve in order to use the model in
10 further calculations.

11 Although several models have been used and developed in the last decades(Lakes, 2009;
12 Mainardi, 2010), the generalized Maxwell model is nowadays widely used due to its
13 simplicity. The generalized Maxwell model is usually represented and fitted with a Prony
14 series (Tzikang, 2000), therefore, hereafter, we use in the text the common term Prony
15 series to refer to that viscoelastic model.

16 On the other hand, the full characterization of a viscoelastic material, most of the times,
17 is not possible due to costs or testing machine limitations. In those cases, analytical or
18 empirical interconversions can be used to complete the characterization of the different
19 moduli of the material (Emri et al., 2005). All the moduli interconversions are fully
20 developed and validated for the Prony series model (Findley et al., 1976; Lakes, 1998;
21 Park and Schapery, 1999; Schapery and Park, 1999; Tschoegl, 2012), being, therefore,
22 easy to implement in finite element analysis (FEA) codes.

23 With the aim of fitting the experimental data to the Prony series model, several methods
24 have been developed (Cost and Becker, 1970; Emri and Tschoegl, 1993; Park and Kim,
25 2001; Ramkumar et al., 1997; R. A. Schapery, 1962; Richard A. Schapery, 1962; Tobolsky,
26 1960; Tobolsky and Murakami, 1959; Tschoegl, 2012; Tschoegl and Emri, 1993). Most of
27 these methods are based on setting a set of discrete times as the first step, followed by
28 the fitting of the rest of the model coefficients. Although several criteria for the
29 allocation of discrete times in the fitting process can be apply (Tschoegl, 2012), usually,
30 its application is not straightforward, so many commercial algorithms (ANSYS, 2013;

1 Herdy, 2003; SIMULIA, 2007; T.A.Instruments, 2001), use an homogeneous distribution
2 (in logarithmic-time scale) to fit the experimental data. This homogeneous distribution
3 for the discrete times τ_i produces accurate fittings when a large number of terms in the
4 Prony's series can be used as well as when the material presents a uniform sigmoidal
5 viscoelastic curve along several decades of time. When short-time curves must be fitted
6 or the relaxation curve shape is not so uniform distributed along time, the homogeneous
7 distribution of the discrete time coefficients could be a significant disadvantage since a
8 large number of coefficients are usually needed or even a reasonable fitting with a
9 Prony's series model is not possible.

10 These short viscoelastic curves with different relaxation ratios are usually obtained for
11 soft-like materials, such as rubbery-like materials, acoustic isolated foams and almost
12 most of the soft tissue biological materials (Barrientos et al., 2016; Fernández et al.,
13 2013; Lamela et al., 2011; Pioletti et al., 1998; Provenzano et al., 2001; Tanaka et al.,
14 2014).

15 Moreover, it must be therefore taken into account that a simpler viscoelastic model with
16 a reduced number of terms is preferred in order to solve complex calculations, e.g. finite
17 element (FE) calculations. Therefore, although a good fitting could be obtained with a
18 large number of terms, a reduced model with fewer terms or parameters, but with the
19 same accuracy, can lead a reduction of the computational time as well as a better
20 compression of the material model.

21 In the present study, a new optimized discrete times method for fitting Prony's
22 coefficients is proposed. The method is based on an optimization algorithm strategy to
23 best allocate the time coefficients along the time scale. The method is validated for
24 fitting the experimental relaxation curve of the temporomandibular Joint (TMJ) disc.

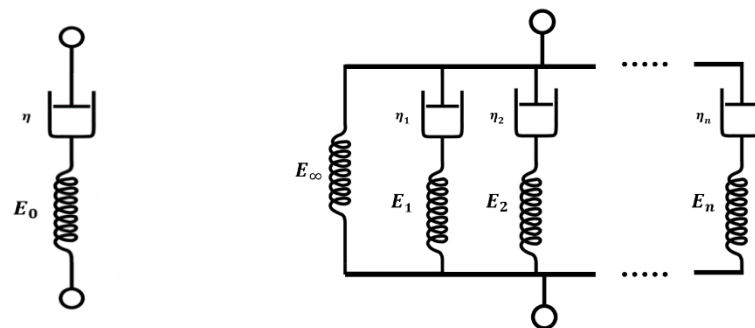
25 Furthermore, the time optimized allocate Prony series coefficients are used to
26 determine the complex moduli (Emri and Tschoegl, 1993; Tschoegl and Emri, 1993) of
27 the TMJ disc. Then, the analytical complex moduli is compared with the experimental
28 complex moduli of the TMJ disc.

29

1

2 Viscoelasticity

3 Viscoelastic materials can be understood like those materials whose properties are
4 somewhere between elastic solids and fluids, i.e. Newtonian fluids. Although its
5 behavior is more complex, this point of view allows an easier understanding of the
6 viscoelastic mathematical models for this kind of materials. Both elastic solid and
7 Newtonian fluid behaviour are each one represented by springs and dashpots,
8 respectively. The combination of these two elements allows building linear viscoelastic
9 models. The simplest model for the relaxation curve is the Maxwell model. The
10 phenomenon of relaxation is produced in a viscoelastic material when is subjected to a
11 constant strain. Under applied constant strain, the stress in the material is dismissing
12 close to zero when the material would be completely relaxed. This behaviour is
13 represented in the Maxwell model with a spring element connected in series with a
14 dashpot element (see Figure 1) (Ferry, 1980; Findley et al., 1976; Lakes, 1998; Tschoegl,
15 2012).



16

17

Figure 1. Individual and Generalized Maxwell Models.

18 When complex relaxation curves have to be fitted, the results obtained with the
19 Maxwell model can be not satisfactory so, in general, the generalized Maxwell model is
20 used. This model is composed of a convenience number of individual Maxwell elements
21 in parallel (see Figure 1). To fit the experimental data with the generalized model, this is
22 usually represented by means of Prony series where each term of the series is identified
23 with one of the individual Maxwell models. The Prony series for the generalized Maxwell
24 model is (Tzikang, 2000):

$$E(t) = E_0 \left[1 - \sum_{i=1}^{n_t} e_i \left(1 - \exp\left(-\frac{t}{\tau_i}\right) \right) \right] \quad (1)$$

where E_0 is the instantaneous modulus of the material, n_t the number of Maxwell terms and (e_i, τ_i) the Prony coefficients (e_i is the i 'th prony constant for the i 'th prony retardation time constant τ_i). The Prony coefficients can be understood as: e_i is the $E(t)$ percentage change in each term of the Prony series whereas τ_i is the discrete time at which the term of Prony series intersects the curve of experimental data.

Once the relaxation modulus of the material has been fitted, the Prony coefficients, (e_i, τ_i) , can be used to obtain by interconversion the components of the complex modulus $E^*(\omega)$, i.e., storage modulus $E'(\omega)$ and loss modulus $E''(\omega)$ (Emri et al., 2005; Park and Schapery, 1999; Schapery and Park, 1999; Tschoegl, 2012):

$$E'(\omega) = E_\infty + \sum_{i=1}^n \frac{\tau_i^2 \omega^2 e_i}{\tau_i^2 \omega^2 + 1} \quad (2)$$

$$E''(\omega) = \sum_{i=1}^n \frac{\tau_i^2 \omega^2 e_i}{\tau_i^2 \omega^2 + 1} \quad (3)$$

2.1 Model fitting with a homogeneous distribution of discrete times

For each number of the serie's terms (which vary from 1 and n_t , being n_t a user convenience number of terms), a Prony series will be built, assuming that τ_i are uniformly spaced in the logarithmic time-space, in the following sequence:

$$\tau_i = \tau_{\min} + \frac{\tau_{\max} - \tau_{\min}}{n_t + 1} i \quad (4)$$

being

$$\tau_{\min} = \log_{10} \min(\tau_k) \quad (5)$$

and

$$\tau_{\max} = \log_{10} \max(\tau_k) \quad (6)$$

1 where $k = 1, \dots, r$ being r the number of experimental data building the master curve.

2 Then, the following optimization problem is proposed:

$$\min S_{err} = \sum_{k=1}^{k=r} \left(\log_{10} E(t_k) - \log_{10} E_{Prorny}(t_k, \vec{\tau}, \vec{\theta}) \right)^2 = f_1(\vec{\theta}) \quad (7)$$

$\forall i = 1, 2, \dots, n_t \rightarrow 0 \leq e_i = g_i(\vec{\theta})$

3

4 To solve the optimization problem, it is converted to the following unconstrained

5 optimization problem:

$$\min S_{err} = \sum_{k=1}^{k=r} \left(\log_{10} E(t_k) - \log_{10} E_{Prorny}(t_k, \vec{\tau}, \vec{\theta}) \right)^2 + \omega \cdot \sum_{i=1}^{n_t} g_i^* = f_1^*(\vec{\theta}) \quad (8)$$

6 In this modified formulation, we have transformed any inequality constraint into a

7 minimization problem by the following way:

$$0 \leq g(\vec{v}) \text{ is equivalent to } \min g^*(\vec{v})$$

being:

(9)

$$g^*(\vec{v}) = \begin{cases} 0 & \text{if } 0 \leq g(\vec{v}) \\ -g(\vec{v}) & \text{if } g(\vec{v}) < 0 \end{cases}$$

8 To solve this issue, Matlab® software is used (MathWorks, 2016) where function

9 “*fminunc*” is applied to solve the optimization problem. This function uses a quasi-

10 Newton method with cubic line search procedure where the method uses the BFGS

11 (Broyden, 1970; Fletcher, 1970; Goldfarb, 1970; Shanno, 1970) formula for updating the

12 approximation of Hessian matrix.

13 **2.2 Model fitting with an optimal distribution of discrete times**

14 In this case, for each number of the series terms n_t , the following optimization problem

15 is solved:

$$\min S_{err} = \sum_{k=1}^{k=r} \left(\log_{10} E(t_k) - \log_{10} E_{Prorny}(t_k, \vec{\tau}) \right)^2 = f_2^*(\vec{\tau}) \quad (10)$$

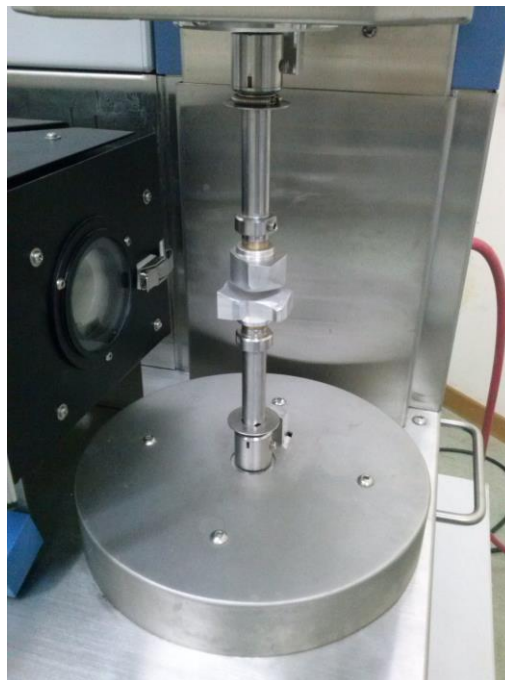
$\tau_i \in [\tau_{\min} \ \tau_{\max}]$

1 where $k = 1, \dots, r$ being r the number of experimental data building the master curve.
2 Internally, in each evaluation of the objective function, τ_i , a similar problem to the one
3 raised with homogeneous distribution optimization is solved. To solve this problem, the
4 function “*fmincon*”, implemented in Matlab® is used (MathWorks, 2016). This command
5 uses a gradient-based method using an interior-point approach (Byrd et al., 2000; Waltz
6 et al., 2006).

7

8 **3 Experimental Data**

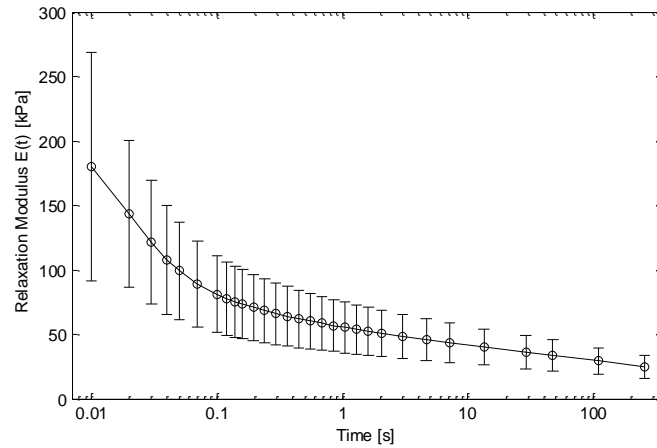
9 To check the proposed optimized fitting method, experimental data from a previous
10 work (Barrientos et al., 2016) was used. The data consist on the viscoelastic curves for
11 the temporomandibular joint (TMJ) disc. Both relaxation and complex modulus were
12 obtained using a DMTA (T.A. Instruments) equipment and 10 specimens (Barrientos et
13 al., 2016). An example of the test set-up is presented in Figure 2. This biological material
14 presents short relaxation curves with a relatively high relaxation rate. The relaxation
15 modulus, as well as the storage and loss components (real and imaginary parts,
16 respectively, of the complex modulus), are presented in Figures 3 and 4. In the figures
17 are presented the mean values together with the standard deviation.



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Figure 2: Experimental test set-up.

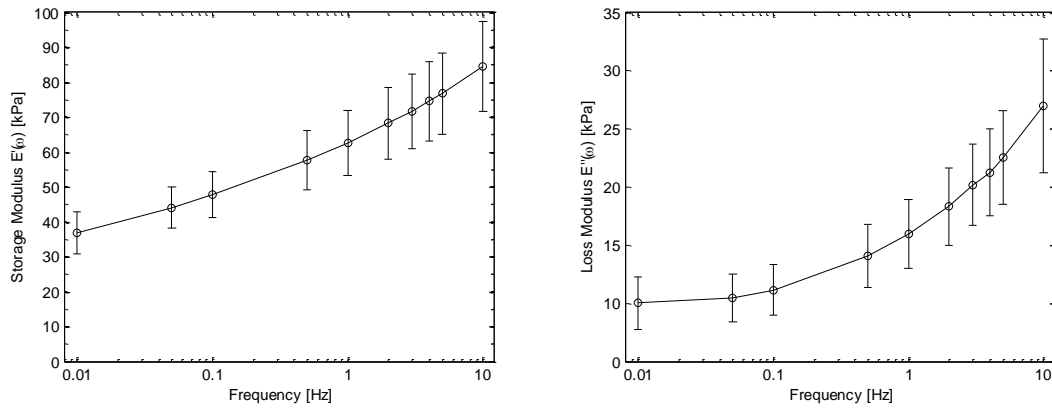


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Figure 3. Relaxation modulus for the whole TMJ disc (Barrientos et al. 2016).

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Figure 4. Storage (E') and loss (E'') moduli for the whole TMJ disc (Barrientos et al. 2016)

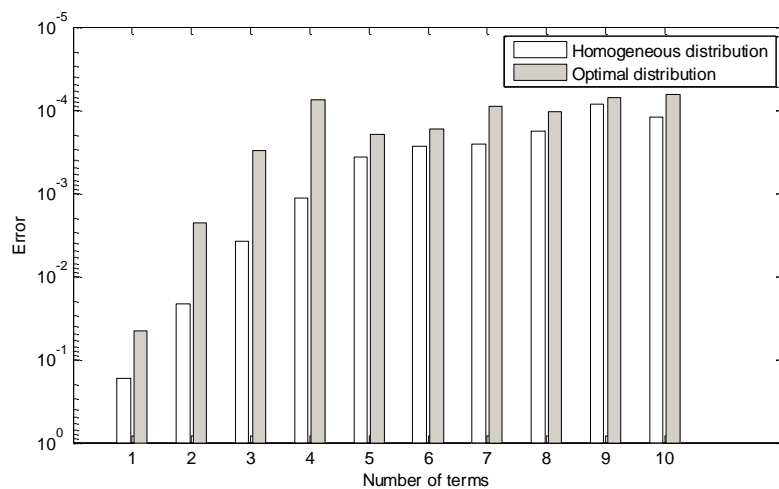
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7 **4 Results**

8 **4.1 Prony series relaxation fitting: optimal and homogeneous distributions.**

9 The mean value of the TMJ disc experimental curves was fitted with both homogeneous
 10 and optimal distributions using from 1 to 10 terms in the Prony series model. The errors
 11 obtained in each model with the homogeneous as well as with the optimal distributions
 12 are presented in Figure 5. It can be seen that the optimal distribution always has an error
 13 lower than in the homogeneous distribution. About 5 terms, the errors between the
 14 homogeneous and optimal distribution decreases but remains always more favorable
 15 for the optimal distribution. For the case analyzed, the optimal distributed model with

1 4 terms can be considered the best model since produces almost the same errors that
 2 the 9 or 10 terms models. The fact that, in this case, the optimal distributed model with
 3 4 terms produces an accurate fitting depends on the time span and relaxation rate of
 4 the experimental curve to fit. So, it would be recommended for other experimental
 5 curves to perform several fittings using in each one a different number of terms. This is
 6 due to the fact that each fitting must be analyzed independently and, therefore, there
 7 is not a direct relation between the number of terms used and the accuracy obtained.
 8 This fact can be observed in figure 4 between the optimal 4 and 5 terms models.



9

10 Figure 5. Evolution of the error with the number of terms of the Prony series for the
 11 TMJ disc.

12 The numerical errors obtained in the fittings for both the homogenous and optimal
 13 discrete times distributions are presented in Table 1.

14

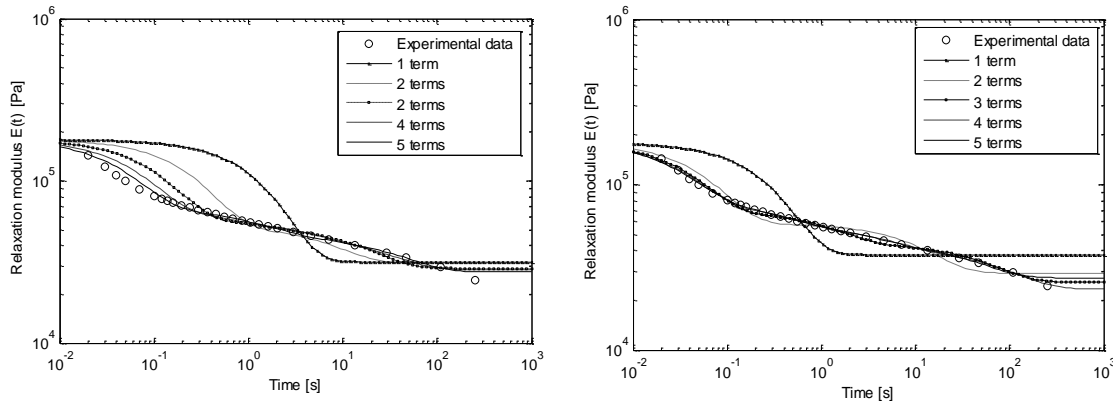
Table 1. Errors obtained in the fittings.

Distribution	Number of terms in the series fitting									
	1	2	3	4	5	6	7	8	9	10
Error [%] Homogeneous	17.0851	2.1464	0.3801	0.1133	0.0369	0.0275	0.0256	0.0181	0.0086	0.0123
Optimal	4.5438	0.2262	0.0306	0.0075	0.0195	0.0167	0.0090	0.0106	0.0071	0.0065

15

16 In Figure 6, the fitting of Prony series with increasing number of terms (from 1 to 5) can
 17 visually be compared for the homogeneous distribution (left) and the optimal

1 distribution (right). From figure 6, it can be inferred that the optimal distribution fitting
2 converges faster than the homogeneous one. As a rough comparison, 6-7 terms are
3 needed in the homogeneous distribution for obtaining a similar error than the 3 terms
4 optimal distribution (see Figure 5).



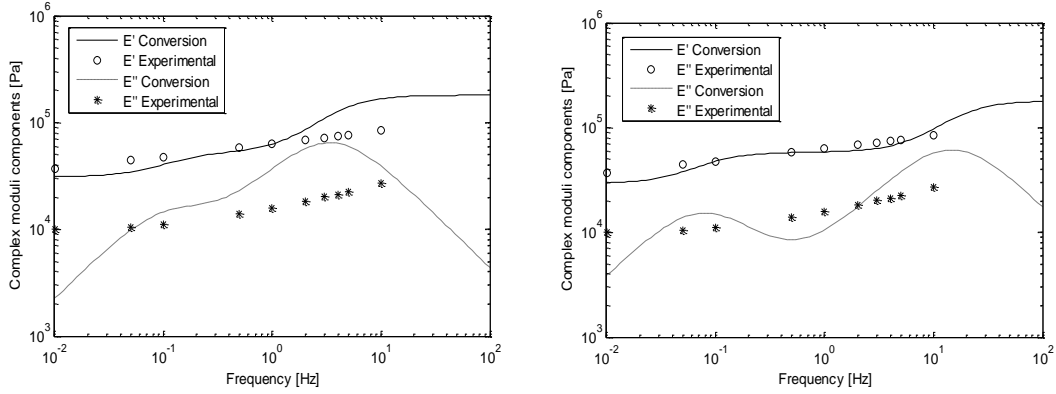
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6 Figure 6. Relaxation curve fittings for both homogeneous (left) and optimal (right)
7 distributions.

9 **4.2 Interconversion between relaxation and complex moduli: homogeneous and** 10 **optimal distributions.**

11 Once the relaxation curves are fitted with the user-convenience terms. The Prony series
12 coefficients can be used to determine the corresponding complex modulus or, that is
13 the same, its real and imaginary components: the storage and loss moduli, respectively
14 (see Eqs. (2) and (3)). Although the optimal time distributions fit the relaxation
15 experimental data with lower errors than the homogeneous time distributions (for the
16 same number of terms), the fact that these optimal discrete times predicts with higher
17 accuracy the complex moduli is not a straightforward step.

18 In figures 6 and 7, the relaxation-complex modulus interconversions are presented using
19 the Prony coefficients obtained for 2 and 4 terms, respectively. In the figures are
20 presented both experimental storage (E') and loss (E'') moduli together with its
21 corresponding predicted curves.

- 1 In both cases, it can be seen that the predicted curves with the optimal distribution
- 2 present a better accuracy than those obtained with the homogeneous distribution.
- 3 Same results are obtained with other comparisons with a different number of terms.

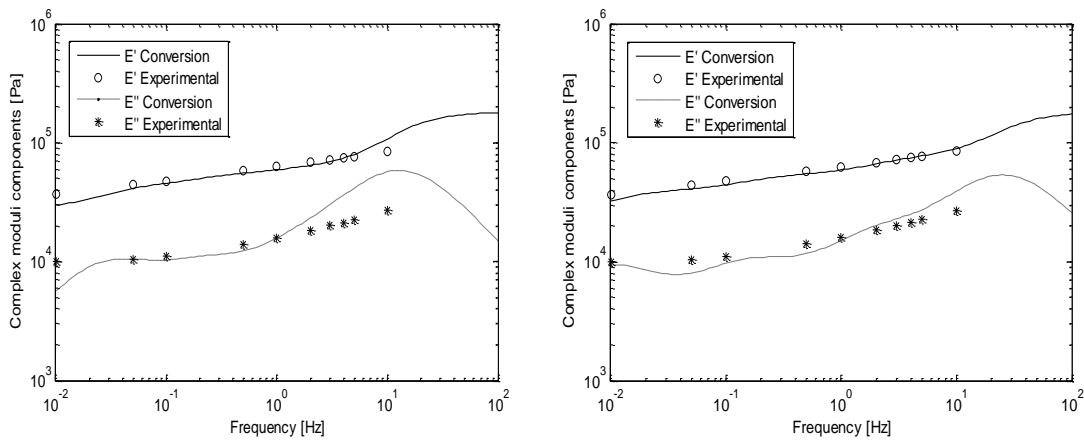


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5 Figure 7: Complex modulus interconversion for 2 Prony series terms with

6 homogeneous distribution (left) and optimal distribution (right).

7



8

9 Figure 8: Complex modulus interconversion for 4 Prony series terms with

10 homogeneous distribution (left) and optimal distribution (right).

11

12 **Conclusions**

13 The generalized Maxwell model, represented by a Prony series is one of the most used

14 viscoelastic models for fitting relaxation experimental data. Although many commercial

15 applications or finite element codes include this model, a homogeneous discrete time

1 distribution, in logarithmic scale, is usually implemented. However, for short time
2 viscoelastic curves or higher relaxations rate, a large number of terms in the Prony series
3 can be needed to obtain accurate results. In most of the cases, a limited number of terms
4 can only be used in the implemented models so the optimization of the fittings can
5 improve the calculations reducing the number of terms used as well as the complexity
6 of the viscoelastic model.

7 In this work, it has been proposed and validated an optimal fitting method for
8 viscoelastic relaxation curves. The optimization process does not previously fix the
9 discrete times of the Prony series, τ_i , being the time coefficients part of the fitting
10 process. This allows the allocation of the time coefficients of the model to produce the
11 best fit for each number of terms selected.

12 The method has been validated for fitting the experimental relaxation curve of the
13 temporomandibular Joint (TMJ) disc. From the results, it can be concluded that for the
14 same number of terms, the optimal distribution presents always lower errors. The errors
15 between the optimal and homogeneous distributions are closer when the number of
16 terms used in the fitting process increase being, nevertheless, always lower for the
17 optimal distributions.

18 For the analyzed case, the model with 4 optimal distributed terms can be considered
19 the best fit with an error of 0.0075%. On the other hand, the best fit for the
20 homogeneous distribution occurs for 9 terms with an error of 0.0086%. Therefore, it can
21 be concluded that the proposed method improves significantly the fitting of the
22 viscoelastic curves when compare with uniform distributed time fittings.

23 Furthermore, time optimized allocate Prony series coefficients were used to determine
24 the complex moduli disc of the TMJ disc. The results show that the optimized fitted
25 model can be also used successfully for the interconversion between the relaxation
26 modulus (time domain viscoelastic properties) and the complex moduli (frequency
27 domain viscoelastic properties). From the results, it is shown that the optimal time
28 distribution predicts with higher accuracy the complex modulus when compared with
29 the homogeneous time distribution, independently of the number of terms used in the
30 interconversion.

1

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1 Appendix A.

2 Table A1. Prony series fitting parameters for both homogeneous and optimal
 3 distributions.

Number of terms	$[E_0 \quad e_1 \quad \tau_1 \quad \cdots \quad e_n \quad \tau_n]$	$[E_0 \quad e_1 \quad \tau_1 \quad \cdots \quad e_n \quad \tau_n]$
1	[180298.480000000 0.824136899437915 1.59394160783480]	[180298.480000000 0.790641298834234 0.322619191008081]
2	[180298.480000000 0.707284956635547 0.293978070709744 0.120770268412372 8.64231077866853]	[180298.480000000 0.676862461948996 0.0685651171281151 0.161502682209828 13.1397290138809]
3	[180298.480000000 0.673376703487496 0.126251399040010 0.0427478277226709 1.59394160783480 0.123798872722651 20.1237362001974]	[180298.480000000 0.617563686189283 0.0463869557979109 0.138900430634949 1.50008759822847 0.100956721878062 65.7721611364916]
4	[180298.480000000 0.633319663251058 0.0760306945400917 0.0522217650402256 0.578066662786207 0.0649518678646969 4.39508107411245 0.0924974124245412 33.4161073308003]	[180298.480000000 0.573375258226682 0.0384396848204708 0.122309844341341 0.492517002572728 0.0818891526813639 6.34991278396463 0.0926709562646039 106.481558689669]
5	[180298.480000000 0.608604338867814 0.0542197440818547 0.0303225376319685 0.293978070709744 0.101624474480116 1.59394160783480 0.0163492061424714 8.64231077866853 0.0911651105378306 46.8583888066941]	[180298.480000000 0.555613598284982 0.0360419070273322 0.122044868675654 0.367926427644592 0.0776018004654576 3.44521016251314 2.89973123637766e-14 8.46034177690573 0.0931430220571901 47.1953714976349]
6	[180298.480000000 0.508707441498211 0.0425870761741618 0.151309350688599 0.181365909333705 0.00672291282557246 0.772384395066749 0.0943870052690803 3.28935937263134 -1.78713787475290e-16 14.0084200968128 0.0920410067233453 59.6577665674181]	[180298.480000000 0.596564191679323 0.0428293235109045 0.113621692730670 0.754783504886141 0.0235777953423940 5.72612215145064 0.0321425785981521 6.69917402670398 4.63150568244530e-14 13.9636166715441 0.0864555822538190 60.0149005687220]
7	[180298.480000000 0.408219752351044 0.0355318725252387 0.235327241728579 0.126251399040010 0.0141788152005874 0.448594870654164 0.0510141503794219 1.59394160783480 0.0589523788855325 5.66357311549749 3.15990723170900e-16]	[180298.480000000 0.546937236520348 0.0364867850655664 0.0385071970807493 0.271652071485464 0.0660473613409926 0.248609442252288 0.0588192209865351 1.30811026892141 0.0567704318759862 5.54205993040787 -1.14727563386985e-15]

	20.1237362001974 0.0900085651950930 71.5034043697626]	20.0788535236374 0.0908857077109137 71.9091369435042]
8	[180298.480000000 0.369990955721492 0.0308630118804967 0.240850502920411 0.0952525521386189 0.0458910141995189 0.293978070709744 0.0188356293543053 0.907304887038130 0.0622974554542280 2.80021620679337 0.0332005677334223 8.64231077866854 -4.06792655116561e-16 26.6727745571547 0.0905142744188743 82.3202174507317]	[180298.480000000 0.589658272922427 0.0432669875222498 0.0303775737583543 0.600112293532432 0.0629286716178740 0.537097786007722 0.00831289587941676 0.780621602225845 0.0326988236074771 2.51791282224508 0.0500052612492851 8.50820603043783 1.25562906426457e-12 26.7087835598032 0.0874363808398120 82.3417865879124]
9	[180298.480000000 0.376344297113462 0.0275736637064206 0.211202644168666 0.0760306945400917 0.0321358387691986 0.209644484454298 0.0432347021656302 0.578066662786207 0.0563927105582293 1.59394160783480 0.0285816881683271 4.39508107411245 0.0281739078871121 12.1188489923801 1.16638469715991e-14 33.4161073308003 0.0884982688808037 92.1404524345236]	[180298.480000000 0.280987293878332 0.0318536667293212 0.265159986799160 0.0423189949558151 0.0896025805541497 0.230252599397086 0.0384312876093378 0.615302475996150 0.0322037787237573 1.64288706474620 0.0403619543960961 4.42464404784351 0.0317649841934840 12.1033969967161 1.08396364800756e-14 33.4194270703965 0.0851108596901352 92.1407522031724]
10	[180298.480000000 0.302657616979265 0.0251448773463986 0.230851656981111 0.0632264869410725 0.0983945553297901 0.158982229097338 0.0171243013736513 0.399758873086139 0.0349530439569653 1.00518880329232 0.0443509236939499 2.52753496742656 0.0405200111308422 6.35545580157655 0.00433176004831986 15.9807159807243 2.94682762349771e-16 40.1833151279606 0.0967305453309271 101.040455047234]	[180298.480000000 0.258058957462417 0.0432890549439342 0.296899712797504 0.0329483246902424 0.0419647103995531 0.182137570185088 0.0436229754722881 0.378282411998683 0.0619516809958969 0.854724969422352 7.05574502841438e-05 2.52434116774581 0.0715741436824561 6.31832276371012 0.00214432685348868 15.9060488163711 0.000319792703734464 40.1359070960688 0.0916967123211249 101.052342008355]